

Let G be a finite group

$$G = \{g_1, g_2, \dots, g_p\}, \quad |G| = p, \quad g_1 \text{ the identity}$$

g_a and g_b are conjugate (in G) if $\exists h \in G$

$$\ni g_a = h^{-1} g_b h$$

There are k classes, $\mathcal{K}_i, i=1, 2, \dots, k$, of conjugate elements.

Let \mathcal{V} be a finite N -dimensional Complex vector space with innerprod $\langle \underline{a}, \underline{b} \rangle, \underline{a}, \underline{b} \in \mathcal{V}$

A representation of G on \mathcal{V} is a homomorphism

$$T: G \rightarrow GL(\mathcal{V}) \quad g \mapsto \underline{T}_g$$

$$\ni \underline{T}_g \underline{T}_h = \underline{T}_{gh} \quad (\text{preserves the group product})$$

The kernel of T is $\text{ker}(T) = \{g \in G \mid \underline{T}_g = \underline{I}\}$

Two representations (reps) T and S are equivalent

$$\text{if } \exists \underline{Q} \in GL(\mathcal{V}) \ni \underline{Q}^{-1} \underline{S}_g \underline{Q} = \underline{T}_g \quad \forall g \in G$$

Theorem: Every rep T of G on \mathcal{V} is equivalent to a unitary rep.

So, we will assume, from now on, T is unitary. That is,

$$\underline{T}_{-g}^\dagger = \underline{T}_{-g}^* = \underline{T}_{-g}^{-1} = \underline{T}_{-g^{-1}}$$

Eq: Elasticity Tensors $\underline{C} = C_{ijkl} \underline{e}_i \otimes \underline{e}_j \otimes \underline{e}_k \otimes \underline{e}_l \in \mathcal{V}^4$

$\mathcal{V} \cong \mathbb{R}^3$; $Q: G \cong SO(3) \rightarrow GL(\mathcal{V})$ is a 3D rep on \mathcal{V}

$$\underline{w} = \underline{Q} \underline{v}$$

For \mathcal{V}^N tensor product rep $\underline{T}_{-Q}^{[N]} = \underline{Q} \otimes \underline{Q} \otimes \dots \otimes \underline{Q}$

\mathcal{V}^2 : consider $\underline{T}^{[2]}$ and $\underline{C} \in GL(\mathcal{V}^2)$

$$\text{Symmetry of } \underline{C} \Rightarrow \underline{T}_{-Q}^{[2]} \underline{C} = \underline{C} \underline{T}_{-Q}^{[2]} \quad \forall Q \in G$$

Alternatively

\mathcal{V}^4 : $\underline{T}^{[4]}$, \underline{C} is invariant:

$$\underline{T}_{-Q}^{[4]} \underline{C} = \underline{C} \quad \forall Q \in G$$

$\underline{W} \subseteq \mathcal{V}$ is an invariant subspace (w.r.t. T) if

$$\underline{w} \in \underline{W} \Rightarrow T_{\underline{g}} \underline{w} \in \underline{W} \quad \forall g \in G, \forall \underline{w} \in \underline{W}$$

skip We can define a rep T' on \underline{W} , $T' = T|_{\underline{W}}$, called the restriction of T on \underline{W} by

$$T'_{\underline{g}} \underline{w} = T_{\underline{g}} \underline{w}, \quad \underline{w} \in \underline{W}$$

Definition: A rep is reducible if \exists a proper subspace \underline{W} of \mathcal{V} which is invariant under T . Otherwise T is irreducible.

So, if T is reducible and \underline{W} is invariant, then we have
(in an appropriate basis)

$$\mathcal{V} = \underline{W} \oplus \underline{W}^{\perp} \quad \text{and} \quad T_{\underline{g}} = \begin{bmatrix} T'_{\underline{g}} & 0 \\ 0 & T''_{\underline{g}} \end{bmatrix} = T' \oplus T''$$

skip

with $T' = T|_{\underline{W}}$, $T'' = T|_{\underline{W}^{\perp}}$

Eg: rotations about a fixed axis: $SO(2) \subset SO(3)$

$$R_{\theta} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & \cos\theta & \sin\theta \\ 0 & -\sin\theta & \cos\theta \end{bmatrix}$$

If T' is reducible, the process is repeated and eventually ends, since \mathcal{V} is finite dimensional.

So, all reps can be reduced to a direct sum of irreps.

$$T = T^{(1)} \oplus T^{(2)} \oplus \dots \oplus T^{(k)}$$

Some of these might be equivalent:

$$T = a_1 T^{(1)} \oplus a_2 T^{(2)} \oplus \dots \oplus a_m T^{(m)} = \sum_{\mu=1}^m \oplus a_{\mu} T^{(\mu)}$$

where all the $T^{(\mu)}$ are inequivalent irreps of dimension

n_{μ} and a_{μ} is the number of times $T^{(\mu)}$ occurs in T .

That is, for every $T \exists Q \in GL(\mathcal{V}) \ni$

$$[Q^{-1} T Q] = \begin{array}{|c|c|c|c|} \hline \begin{matrix} T_g^{(1)} \\ T_g^{(1)} \\ \vdots \\ T_g^{(1)} \end{matrix} & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} & \dots & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ \hline \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} & \begin{matrix} T_g^{(2)} \\ T_g^{(2)} \\ \vdots \\ T_g^{(2)} \end{matrix} & \dots & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ \hline \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} & \begin{matrix} \vdots \\ \vdots \\ \vdots \end{matrix} & \dots & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} \\ \hline \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} & \begin{matrix} 0 \\ \vdots \\ 0 \end{matrix} & \dots & \begin{matrix} T_g^{(m)} \\ T_g^{(m)} \\ \vdots \\ T_g^{(m)} \end{matrix} \\ \hline \end{array} \begin{array}{l} \left. \vphantom{\begin{matrix} T_g^{(1)} \\ T_g^{(1)} \\ \vdots \\ T_g^{(1)} \end{matrix}} \right\} a_1 \text{ times} \\ \left. \vphantom{\begin{matrix} T_g^{(2)} \\ T_g^{(2)} \\ \vdots \\ T_g^{(2)} \end{matrix}} \right\} a_2 \text{ times} \\ \vdots \\ \left. \vphantom{\begin{matrix} T_g^{(m)} \\ T_g^{(m)} \\ \vdots \\ T_g^{(m)} \end{matrix}} \right\} a_m \text{ times} \end{array}$$

$\forall g \in G$

So, irreps are fundamental & finding all irreps of G is crucial.

Knowing the above allows solving $T_g c = c T_g$ and $T_g c = c$ systematically

We start with Schur's lemma

Let T and T' be $p \times p$ and $q \times q$ complex matrix irreps of G , and let A be a $q \times p$ matrix \ni

$$\underline{T}_g' \underline{A} = \underline{A} \underline{T}_g \quad \forall g \in G$$

Then,

if T & T' are nonequivalent, $\underline{A} = \underline{0}$.

otherwise, $\underline{A} = \lambda \underline{I}$, $\lambda \in \mathbb{C}$.

(Note, these only depend on irreducibility and finite-dim of T & T' , not the structure of G)

This leads to the orthogonality relations

$$\sum_{g \in G} T_{ij}^{(\mu)}(g) T_{kl}^{(\nu)*}(g) = \left(\frac{p}{n_\mu} \right) \delta_{ik} \delta_{jl} \delta_{\mu\nu}$$

(Recall
 $p = |G|$)

$$i, j = 1, 2, \dots, n_\mu$$

$$n_\mu = \dim T^{(\mu)}$$

$$k, l = 1, 2, \dots, n_\nu$$

$$n_\nu = \dim T^{(\nu)}$$

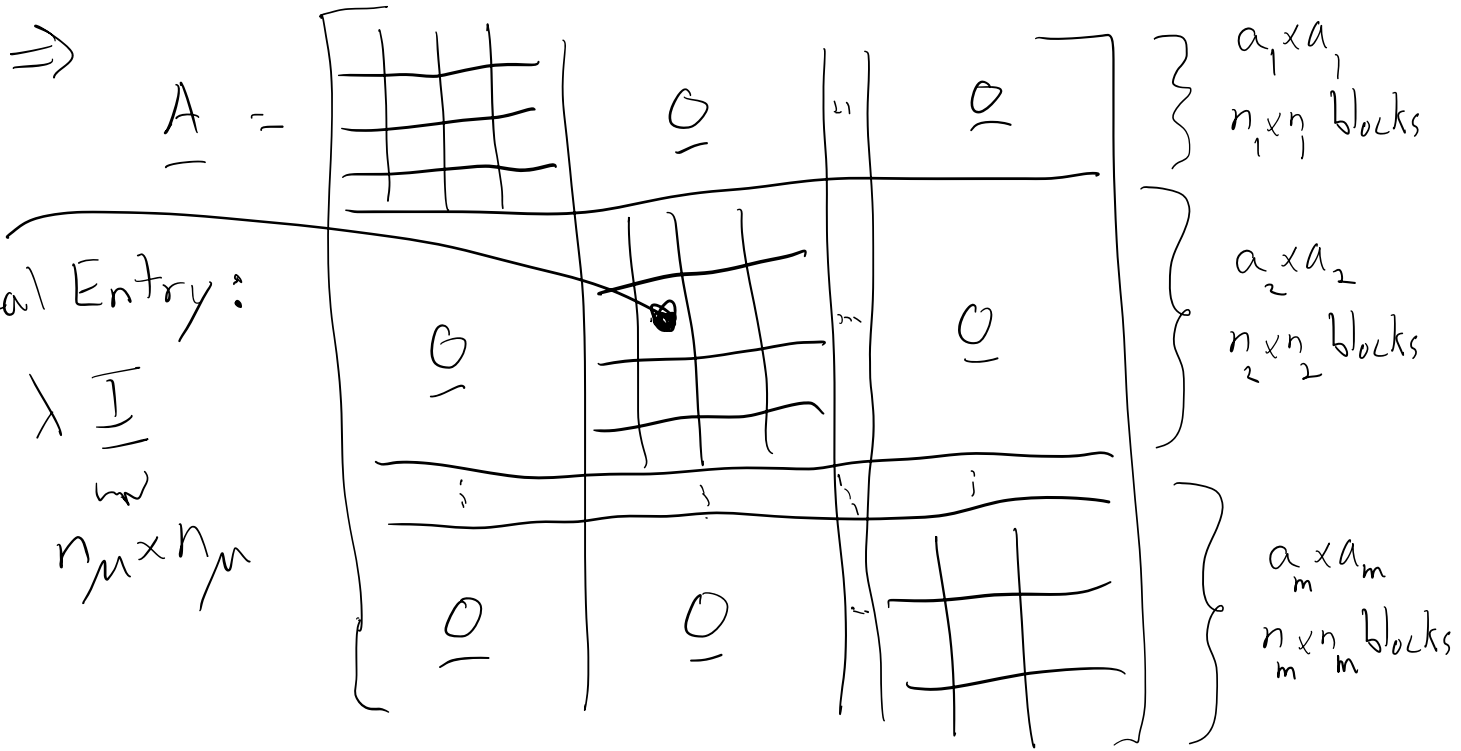
$$\mu, \nu = 1, 2, \dots, m$$

$$m = \# \text{ irreps of } G$$

We use these orthogonality relations to find the irreps.

Shur also implies properties for linear operators that commute with the rep:

$$\underline{T}_g \underline{A} = \underline{A} \underline{T}_g ; T = \sum \oplus_n T^{(n)}$$



Eg: \underline{V} for $SO(2)$ state: $\underline{Q} \underline{V} = \underline{V} \underline{Q}$; $\underline{Q} = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$

$\Rightarrow \underline{V} = \begin{bmatrix} \sigma_{11} & 0 & 0 \\ 0 & \sigma_{22} & 0 \\ 0 & 0 & \sigma_{22} \end{bmatrix}$

$\left. \begin{matrix} \sigma_{11} \\ 0 \end{matrix} \right\} \begin{matrix} 1 \\ 1 \end{matrix}$
 $\left. \begin{matrix} 0 \\ \sigma_{22} \\ 0 \end{matrix} \right\} \begin{matrix} 1 \\ 2 \times 2 \end{matrix}$

Eg:

$$\underline{T}_g \underline{C} = \underline{C} \underline{T}_g$$

$g \in$ cubic group

roughly $\underline{T}^{[2]} = 1 \underline{T}^{(1)} + 1 \underline{T}^{(2)} + 1 \underline{T}^{(3)}$
 $n_1=1, n_2=2, n_3=3$

Voigt notation

	$\underline{A} \underline{B} \underline{B}$				}	$\underline{0}$
	$\underline{B} \underline{A} \underline{B}$					
	$\underline{B} \underline{B} \underline{A}$				}	$\underline{0} \ \underline{0} \ \underline{0}$
	$\underline{0}$					

\Rightarrow

	$(\underline{A}+2\underline{B})$				}	$\underline{0}$
					}	$(\underline{A}-\underline{B}) \underline{I}_{3 \times 2}$
					}	$\underline{0}$

Now, we learn more about irreps!

Define the P -dimensional complex vector space \mathcal{V}_G consisting of all elements of the form

$$\underline{x} = \sum_{g \in G} x(g) \cdot g, \quad x(g) \in \mathbb{C}$$

with inner product

$$\langle \underline{x}, \underline{y} \rangle = \frac{1}{P} \sum_{g \in G} x(g) y^*(g)$$

in essence the $g_i \in G$ form an Ortho basis of \mathcal{V}_G

Notice that, for fixed μ, i, j , $T_{ij}^{(\mu)}(g)$ can be viewed as the components of a vector in \mathcal{V}_G !

The inner product of \mathcal{V}_G shows these form an orthogonal set in \mathcal{V}_G :

$$\begin{aligned} \langle T_{ij}^{(\mu)}, T_{kl}^{(\nu)} \rangle &= \frac{1}{P} \left\{ \sum_{g \in G} T_{ij}^{(\mu)}(g) T_{kl}^{(\nu)*}(g) \right\} \\ &= \frac{1}{P} \left\{ \left(\frac{P}{n_\mu} \right) \delta_{ik} \delta_{jl} \delta_{\mu\nu} \right\} \text{ by Schur.} \\ &= \frac{1}{n_\mu} \delta_{ik} \delta_{jl} \delta_{\mu\nu} \end{aligned}$$

Thus:

$$\sum_{\mu=1}^m n_{\mu}^2 \leq P, \text{ in fact } = P$$

This is a major constraint on the # of irreps of G and the n_{μ}

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To prove equality (although we will not do so here) we need:
(this does depend on the structure of G)

On \mathcal{V}_G we construct a rep, the right regular rep, R

$$R_{-h} x = \sum_{g \in G} [R_{-h} x](g) \cdot g \equiv \sum_{g \in G} x(gh) \cdot g$$

check

$$R_{-h_1} R_{-h_2} x = R_{-h_1} \left(R_{-h_2} x \right) = R_{-h_1} \left(R_{-h_2} \sum_{g \in G} x(g) \cdot g \right)$$

$$y = \sum_{g \in G} y(g) g = \sum_{g \in G} x(gh_2) g$$

$$y(g) = x(gh_2)$$

$$= R_{-h_1} y = R_{-h_1} \sum_{g \in G} y(g) \cdot g$$

$$\stackrel{\cong}{=} \sum_{s \in G} z(s) g = \sum_{g \in G} y(gh_2) g \Rightarrow z(g) = y(gh_1)$$

$$\Rightarrow z(g) = y(gh_1) = x(gh_1 h_2)$$

$$\Rightarrow R_{-h_1} R_{-h_2} = R_{-h_1 h_2}$$

To further constrain the irreps, we introduce

Group Characters

$$\chi^{(\mu)}(g) = \text{tr}(T_g^{(\mu)}) \in \mathcal{V}_G$$

since $\text{tr}(\underline{A}\underline{B}) = \text{tr}(\underline{B}\underline{A})$, we get characters are constant on conjugacy classes of G :

$$g_j = h^{-1} g_i h ; \chi^{(\mu)}(g_j) = \chi^{(\mu)}_{h^{-1} g_i h} = \chi^{(\mu)}_{g_i h^{-1} h} = \chi^{(\mu)}_{g_i}$$

thus, each $\chi^{(\mu)}$ is fully characterized by k numbers the number of conjugacy classes of G .

It follows that the $\chi^{(\mu)}$ span a k -dimensional subspace of \mathcal{V}_G . Indeed,

$$\begin{aligned} \langle \chi^{(\mu)}, \chi^{(\nu)} \rangle &= \frac{1}{P} \sum_{g \in G} \chi^{(\mu)}(g) \chi^{(\nu)}(g)^* \\ &= \frac{1}{P} \sum_{g \in G} \left(\sum_i T_{ii}^{(\mu)} \right) \left(\sum_j T_{jj}^{(\nu)} \right)^* \\ &= \frac{1}{P} \sum_i \sum_j \left(\sum_{g \in G} T_{ii}^{(\mu)} T_{jj}^{(\nu)*} \right) \end{aligned}$$

$$\begin{aligned}
&= \frac{1}{P} \sum_i \sum_j \left(\frac{P}{n_\mu} \delta_{ij} \delta_{ij} \delta_{\mu\nu} \right) \\
&= \frac{1}{n_\mu} \delta_{\mu\nu} \left(\underbrace{\sum_i \sum_j \delta_{ij} \delta_{ij}}_{n_\mu} \right) \\
&= \delta_{\mu\nu}
\end{aligned}$$

It can be shown that every vector in this k -dim space is a linear combination of the $\chi^{(\mu)}$.

So the $\chi^{(\mu)}$ are an O.N. basis for k -dim space

\Rightarrow the number of inequivalent irreps is k .

$$\sum_{\mu=1}^k n_\mu^2 = P \quad ; \quad P = |G| \quad ; \quad n_\mu = \dim(T^{(\mu)})$$

$k = \# \text{ classes}$

$\langle \chi, \chi \rangle = 1$ iff T is irred.

A second orthogonality relation:

Define m_i $i=1, 2, \dots, k$ to be the size of the i^{th} conjugacy class, \mathcal{K}_i , and $\chi_i^{(\mu)}$ its char^{ter}, it can be shown:

$$\sum_{\mu=1}^k \chi_i^{(\mu)} \overline{\chi_j^{(\mu)}} = \frac{P}{m_i} \delta_{ij}$$

Character tables

	$1 \mathcal{K}_1$	$m_2 \mathcal{K}_2$		$m_k \mathcal{K}_k$
$\chi^{(1)}$	$\chi_1^{(1)}$	$\chi_2^{(1)}$		$\chi_k^{(1)}$
$\chi^{(2)}$	$\chi_1^{(2)}$	$\chi_2^{(2)}$...	$\chi_k^{(2)}$
...				
$\chi^{(k)}$	$\chi_1^{(k)}$	$\chi_2^{(k)}$		$\chi_k^{(k)}$

- $\sum_{m=1}^k n_m^2 = p$

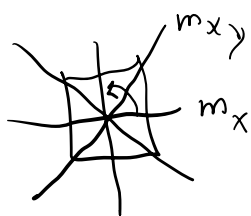
- $\chi_1^{(m)} = \chi^{(m)}(g_1) = n_m$, $m=1, \dots, k$

- $\chi_i^{(1)} = 1$, $i=1, \dots, k$

- $\sum_{m=1}^k \chi_i^{(m)} \overline{\chi_j^{(m)}} = \frac{p}{m_i} \delta_{ij}$

- $\langle \chi^{(m)}, \chi^{(v)} \rangle = \sum_{i=1}^k \chi_i^{(m)} \overline{\chi_j^{(v)}} m_i = \delta_{mv}$

Eg: $G = C_{4v} = \{e, R_{90}, R_{180}, R_{270}, m_x, m_y, m_{xy}, m_{\bar{x}y}\}$



$p=8$

$m_1=1$

$m_2=2$

$m_3=2$

$k=5$

$\mathcal{K}_1 = \{e\}$

$\mathcal{K}_2 = \{R_{180}\}$

$\mathcal{K}_3 = \{R_{90}, R_{270}\}$

$m_4=2$

$m_5=2$

$\mathcal{K}_4 = \{m_x, m_y\}$

$\mathcal{K}_5 = \{m_{xy}, m_{\bar{x}y}\}$

$$n_1^2 + n_2^2 + n_3^2 + n_4^2 + n_5^2 = 8 \Rightarrow 1^2 + 1^2 + 1^2 + 1^2 + 2^2 = 8$$

C_{2V}	$1\mathcal{K}_1$	$1\mathcal{K}_2$	$2\mathcal{K}_3$	$2\mathcal{K}_4$	$2\mathcal{K}_5$
$\chi^{(1)}$	1	1	1	1	1
$\chi^{(2)}$	1	1	1	-1	-1
$\chi^{(3)}$	1	1	-1	1	-1
$\chi^{(4)}$	1	1	-1	-1	1
$\chi^{(5)}$	2	-2	0	0	0

Additional Theorems :

fixed point space : $T_g \underline{v} = \underline{v} \quad \forall g \in G$

Projection:

$$P = \frac{1}{P} \sum_{g \in G} \chi^{(1)}(g) T_g = \frac{1}{P} \sum_{g \in G} T_g$$

$$T_g \underline{c} = \underline{c} \Rightarrow \underline{c} \text{ is in fixed point space}$$

$$T = \sum_{\mu=1}^k \oplus a_{\mu} T^{(\mu)}$$

$$a_{\mu} = \frac{n_{\mu}}{P} \sum_{g \in G} \chi(g) \chi^{(\mu)*}(g) \quad ; \quad \chi(g) = \text{tr}(T_g)$$

References:

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