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Long time asymptotics for homoenergetic solutions of the Boltzmann equation. Hyperbolic-dominated case

Long time asymptotics for homoenergetic solutions of the Boltzmann equation. Hyperbolic-dominated case

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Abstract

In this paper we continue the formal analysis of the long-time asymptotics of the homoenergetic solutions for the Boltzmann equation that we began by James *et al* (2019 *J. Nonlinear Sci.* **29** 1943–73). They have the form $f(x, v, t) = g(v - L(t)x, t)$ where $L(t) = A(I + tA)^{-1}$ where A is a constant matrix. Homoenergetic solutions satisfy an integro-differential equation which contains, in addition to the classical Boltzmann collision operator, a linear hyperbolic term. Depending on the properties of the collision kernel the collision and the hyperbolic terms might be of the same order of magnitude as $t \to \infty$, or the collision term could be the dominant one for large times, or the hyperbolic term could be the largest. The first case has been rigorously studied by James *et al* (2019 *Arch. Ration. Mech. Anal.* **231** 787–843). Formal asymptotic expansions in the second case have been obtained by James *et al* (2019 *J. Nonlinear Sci.* **29** 1943–73). All the solutions obtained in this case can be approximated by Maxwellian distributions with changing temperature. In this paper we focus in the case where the hyperbolic terms are much larger than the collision term for large times (hyperbolic-dominated behaviour). In the hyperbolic-dominated case it does not seem to be possible to describe in a simple way all the long time asymptotics of the solutions, but we discuss several physical situations and formulate precise conjectures. We give explicit formulae for the relationship between density, temperature and entropy for these solutions. These formulae differ greatly from the ones at equilibrium.

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(Some figures may appear in colour only in the online journal)

1. Introduction

In this paper we continue the study of the long time asymptotics of the homoenergetic solutions of the Boltzmann equation which do not exhibit self-similar behaviours. We began this analysis in [18] where the self-similar case was considered and, in [19], where solutions behaving asymptotically as Maxwellian distributions with changing temperature were studied.

The class of solutions under consideration is motivated by an invariant manifold of solutions of the equations of classical molecular dynamics with certain symmetry properties ([10, 11]).

We shortly recall the main properties of this manifold (we refer to [18] for a more detailed description). Suppose that we consider a matrix $A \in M_{3\times3}(\mathbb{R})$, satisfying $\det(I + tA) > 0$ for $t \in [0, a)$ with $a > 0$, and the orthonormal vectors e_1, e_2, e_3 in $\mathbb{R}^3$. We consider *M simulated atoms* with positive masses $m_1, \ldots, m_M$ subject to the equations of molecular dynamics yielding solutions $y_k(t) \in \mathbb{R}^3$, $0 \leqslant t < a$, $k = 1, \ldots, M$. Moreover, we denote as $y_{\nu,k}(t)$, $\nu = (\nu_1, \nu_2, \nu_3) \in \mathbb{Z}^3$ the positions of the *non-simulated atoms* which are given by

$$y_{\nu,k}(t) = y_k(t) + (I + tA)(\nu_1 e_1 + \nu_2 e_2 + \nu_3 e_3), \quad \nu = (\nu_1, \nu_2, \nu_3) \in \mathbb{Z}^3, k = 1, \ldots, M. \tag{1.1}$$

For $k = 1, \ldots, M$ we denote as $f_k : \cdots \mathbb{R}^3 \times \mathbb{R}^3 \times \mathbb{R}^3 \cdots \to \mathbb{R}$ the force on simulated atom k which depends on the positions of all the atoms. Assuming that f_k satisfies the usual conditions of frame-indifference and permutation invariance [10] we have

$$m_k \ddot{y}_k = f_k(\ldots, y_{\nu_1,1}, \ldots, y_{\nu_1,M}, \ldots, y_{\nu_2,1}, \ldots, y_{\nu_2,M}, \ldots),$$
$$y_k(0) = y_k^0, \quad \dot{y}_k(0) = v_k^0, \quad k = 1, \ldots, M. \tag{1.2}$$

Using (1.1) we can reduce (1.2) to a system of ODEs for the motions of the simulated atoms, i.e. $y_k(t)$, $k = 1, \ldots, M$.

It is shown in [10, 11] that in spite of the fact that the motions of the nonsimulated atoms are only given by the formulae (1.1), the equations of molecular dynamics (1.2) are exactly satisfied for each nonsimulated atom.

As discussed in [18], these results on molecular dynamics have a simple counterpart in terms of the molecular density function of the kinetic theory. The classical Boltzmann equation reads as

$$\partial_t f + v\partial_x f = \mathbb{C}f(v), \quad f = f(t, x, v)$$
$$\mathbb{C}f(v) = \int_{\mathbb{R}^3} dv_* \int_{S^2} d\omega B\left(n \cdot \omega, |v - v_*|\right) \left[f' f_*' - f_* f\right], \tag{1.3}$$

where S^2 is the unit sphere in $\mathbb{R}^3$ and $n = n(v, v_*) = \frac{(v - v_*)}{|v - v_*|}$. Let be (v, v_*) a pair of incoming velocities (see figure 1). The outgoing velocities (v', v_*') are given by the collision rule

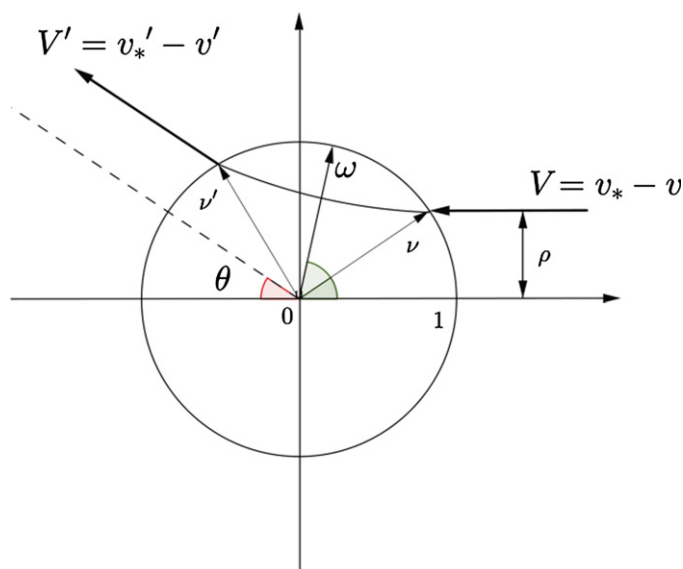$$v' = v + ((v_* - v) \cdot \omega)\omega, \tag{1.4}$$

Figure 1. The two-body scattering. The scalar $\rho \in [-1, 1]$ is the impact parameter, and $\theta = \theta(\rho, |V|)$ is the scattering angle. The scattering vector of (1.4), (1.5) is the unit vector $\omega = \omega(v, V)$.

$$v_*' = v_* - ((v_* - v) \cdot \omega)\,\omega, \tag{1.5}$$

where $\omega = \omega(v, V)$ is the unit vector bisecting the angle between the incoming relative velocity $V = v_* - v$ and the outgoing relative velocity $V' = v_*' - v'$ as specified in figure 1.

We will use in the rest of the paper the standard convention $f = f(t, x, v)$, $f_* = f(t, x, v_*)$, $f' = f(t, x, v')$, $f_*' = f(t, x, v_*')$.

The collision kernel $B(n \cdot \omega, |v - v_*|)$ is proportional to the cross section for the scattering problem associated to the collision between two particles. We will assume that it is homogeneous in $|v - v_*|$ and we will denote its homogeneity by γ, i.e.,

$$B(n \cdot \omega, \lambda |v - v_*|) = \lambda^\gamma B(n \cdot \omega, |v - v_*|), \quad \lambda > 0. \tag{1.6}$$

The homogeneity γ is related to the properties of the interaction potential between particles. We recall that in the standard literature in kinetic theory (see [25]), interaction potentials with the form $V(x) = \frac{1}{|x|^{\nu-1}}$ have homogeneity $\gamma = \frac{\nu-5}{\nu-1}$ for the kernel B.

It is possible to find solutions of the Boltzmann equation (1.3) that have the same statistics as the molecular dynamics simulation for discrete systems described above (see (1.1)). We refer to [18] for details. Thus, the analogous of the ansatz (1.1) in terms of the particle velocities can be written as:

$$f(t, x, v) = g\left(t, v - A(I + tA)^{-1}x\right). \tag{1.7}$$

The term $A(I + tA)^{-1}$ arises from conversion to the Eulerian form of the kinetic theory.

An alternative way of deriving (1.7) is by means of the theory of *equidispersive solutions* for the Boltzmann equation. These are solutions of the Boltzmann equation with the form

$$f(t, x, v) = g(t, w) \quad \text{with } w = v - \xi(t, x). \tag{1.8}$$

Under mild smoothness conditions, solutions with the form (1.8) exist if $\xi(t, x) = A(I + tA)^{-1}x$ (see [18]). Formally, if *f* is a solution of the Boltzmann equation (1.3) of the form (1.7) the function *g* satisfies

$$\partial_t g - (L(t)\,w) \cdot \partial_w g = \mathbb{C}g(w) \tag{1.9}$$

where the collision operator $\mathbb{C}$ is defined as in (1.3). These solutions are called *homoenergetic solutions* and were introduced by Galkin [13] and Truesdell [23] and later considered both in the physical and mathematical literature. Most of the references in the physical literature focus on the evolution of the moments for the homoenergetic solutions, assuming that they exist, providing a large amount of information about quantities like the typical deviation of the velocity and similar quantities. For instance, we refer to [13–15, 21–23], as well as to the books [17, 24]. On the mathematical side, the well-posedness of solutions to (1.9) in an L^1 setting has been considered for a particular choice of the deformation matrix *L*(*t*) in [6–8], or, in the class of Radon measures, in [18]. Invariance properties of solutions to the Boltzmann equation have been considered in [5] in two dimensions.

The properties of the solutions of (1.9) for large times *t* depend greatly on the homogeneity γ of the kernel yielding the cross section of the collision operator $\mathbb{C}g$. Some insights on the role of γ can be obtained in the following way. In systems subject to shear deformations the average velocity of the particles tends to increase (due to heating effects). Therefore, the role of the collisions becomes more relevant for larger times if the homogeneity of the kernel γ is positive and less relevant if γ is negative. On the contrary, expanding gases (under dilatations) cool down and thus the average velocity of the particles in the gas decreases. Then, for $\gamma < 0$ the role of collisions becomes more important and vice versa for $\gamma > 0$. This behaviour of the collision term must be weighted in against the behaviour of the hyperbolic term $L(t)\,w \cdot \partial_w g$ in order to determine which is the dominant effect for long times.

In [18] we have focused on the analysis of solutions of (1.9) for which the terms $L(t)\,w \cdot \partial_w g$ and $\mathbb{C}g(w)$ are of the same order of magnitude. We have rigorously proved in [18] the existence of self-similar solutions in the class of homoenergetic flows when the collision kernel describes the interaction between Maxwell molecules, which corresponds to homogeneity $\gamma = 0$. In all the cases when such self-similar solutions exist, the terms $L(t)\,w \cdot \partial_w g$ and $\mathbb{C}g(w)$ have a comparable size as $t \to \infty$. We remark that the existence of self-similar solutions has been obtained also for Boltzmann equations related to the theory of granular gases. See for instance [16].

In [19] we considered the case in which the collision terms are the dominant ones as $t \to \infty$. The solutions obtained in that paper are approximately Maxwellians, with a time dependent temperature whose evolution is obtained using a suitable adaptation of the standard Hilbert expansion.

Notice that additional regularity and integrability assumptions on the collision kernel *B* would be needed in order to make rigorous the formal asymptotics presented in this paper and in [19]. For instance, precise assumptions on the collision kernel *B* which allow to prove rigorously the existence of self-similar solutions, have been considered in [18].

Finally, it turns out that there are also choices of *L*(*t*) and collision kernels *B* for which the scaling properties of the different terms imply that the hyperbolic terms are much more important than the collision terms. This hyperbolic-dominated case is the one studied in this paper. We emphasize that in this case there is a large variety of different asymptotic behaviours for the homoenergetic flows.

For instance, in some particular cases discussed in this paper the effect of the collision terms becomes negligible as $t \to \infty$ and the distribution of particle velocities is asymptotically given by the hyperbolic terms in (1.9), namely $L(t)\,w \cdot \partial_w g$. We will refer to this case as 'frozen

collision regime'. From a physical point of view in this regime one given particle collides only a finite number of times as $t \to \infty$. However we will find also situations in which, in spite of becoming increasingly small as $t \to \infty$, the collision term $\mathbb{C}g(w)$ plays a crucial role characterizing the distribution of velocities of the particles. This is due to the fact that the mean free path increases to ∞ as $t \to \infty$ but, at the same time, for each given particle the probability of having infinitely many collisions in the time interval $(0, \infty)$ is equal to one. This case is very interesting, but it is also the case for which we have more fragmentary results (cf section 3). In order to shed some light on the behaviour of the particle distribution g, we introduce in section 3.5 a simplified model, which does not correspond to any Boltzmann equation, but contains several of the main characteristics which can be found for homoenergetic solutions in the case in which the hyperbolic terms are dominant. The behaviour of the velocity distributions that we obtain in that case is quite different from the ones obtained in the previous cases, since these distributions cannot be approximated by Maxwellians, but they are also not self-similar.

We notice that similar situations in which the interactions between the particles become negligible for large times, have been studied in several classes of kinetic equation ([1–3]). In those papers the expansion of a finite amount of mass of the gas in the whole space is considered.

The plan of the paper is the following. In section 2 we summarize the most relevant properties of homoenergetic solutions of the Boltzmann equation which have been obtained in [18, 19].

In section 3 we discuss several results that we have obtained about hyperbolic-dominated homoenergetic flows. In particular, in section 3.5, we describe some results for a simple toy model for which the long time asymptotics is hyperbolic-dominated. It is possible to obtain analytically information about the long time asymptotics of the solutions of the toy model and hopefully this could shed some light about the behaviour of more complex hyperbolic-dominated fluxes. Section 4 contains formulae about the behaviour of the entropy for the solutions derived here and in [18, 19]. This allows to estimate how far from equilibrium are the asymptotics of the obtained solutions.

In section 5 we conclude presenting an overview of the results obtained in this paper as well as in [18, 19].

2. Homoenergetic solutions of the Boltzmann equation

We assume that the molecular density function $f(t, x, v)$ satisfies (1.3), namely

$$\partial_t f + v \partial_x f = \mathbb{C}f(v), \quad f = f(t, x, v)$$

$$\mathbb{C}f(v) = \int_{\mathbb{R}^3} dv_* \int_{S^2} d\omega B\left(n \cdot \omega, |v - v_*|\right) \left[f' f'_* - f_* f\right].$$

Homoenergetic solutions of (1.3) defined in [13, 23] (see also [24]) are solutions of the Boltzmann equation having the form

$$f(t, x, v) = g(t, w) \quad \text{with } w = v - \xi(t, x). \tag{2.1}$$

In order to have solutions of (1.3) with the form (2.1) for a sufficiently large class of initial data we must have

$$\frac{\partial \xi_k}{\partial x_j} \text{ independent on } x \text{ and } \partial_t \xi + \xi \cdot \nabla \xi = 0. \tag{2.2}$$

The first condition implies that ξ is an affine function on x. In [18, 19] we restricted to the case in which ξ is a linear function of x for simplicity. The general solution of this equation is

$$\xi(t, x) = L(t)x + B(t),\tag{2.3}$$

where $L(t) \in M_{3\times3}(\mathbb{R})$ is a 3×3 real matrix and $B(t) \in \mathbb{R}^3$. Then, the second equation in (2.2) holds if and only if

$$\frac{\mathrm{d}L(t)}{\mathrm{d}t} + (L(t))^2 = 0, \quad L(0) = A,\tag{2.4}$$

for some initial condition $A \in M_{3\times3}(\mathbb{R})$, and

$$\frac{\mathrm{d}B(t)}{\mathrm{d}t} + L(t)B(t) = 0, \quad B(0) = B_0,\tag{2.5}$$

for some initial condition $B_0 \in \mathbb{R}^3$.

The unique continuous solutions of (2.4) and (2.5) are given by

$$L(t) = (I + tA)^{-1}A = A(I + tA)^{-1},\tag{2.6}$$

$$B(t) = (I + tA)^{-1}B_0 = B_0(I + tA)^{-1}\tag{2.7}$$

defined on a maximal interval of existence $[0, a)$. On the interval $[0, a)$, $\det(I + tA) > 0$.

We observe that the function $g(t, w)$ solves (1.9) even if we choose $\xi(x, t)$ as the affine function (2.3).

We now recall the classification of homoenergetic flows which has been obtained in [18] (cf theorem 3.1). More precisely, we describe the long time asymptotics of the linear term of $\xi(t, x)$, namely $L(t)x = (I + tA)^{-1}Ax$ (cf (2.3) and (2.6)). Notice that the linear part is the only one which plays a relevant role in the long time asymptotics of the solution $g(t, w)$.

It has been proved in [18] (cf theorem 3.1), using all the possible Jordan decompositions, that for any matrix $A \in M_{3\times3}(\mathbb{R})$ such that $\det(I + tA) > 0$ for $t \geqslant 0$ the possible long time asymptotics of the matrix $L(t) = (I + tA)^{-1}A$ is one of the following:

Case (i) homogeneous dilatation:

$$L(t) = \frac{1}{t}I + O\left(\frac{1}{t^2}\right) \quad \text{as } t \to \infty.\tag{2.8}$$

Case (ii) cylindrical dilatation ($K = 0$), or case (iii) cylindrical dilatation and shear ($K \neq 0$):

$$L(t) = \frac{1}{t}\begin{pmatrix} 1 & 0 & K \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix} + O\left(\frac{1}{t^2}\right) \quad \text{as } t \to \infty.\tag{2.9}$$

Case (iv) planar shear:

$$L(t) = \frac{1}{t}\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & K \\ 0 & 0 & 1 \end{pmatrix} + O\left(\frac{1}{t^2}\right) \quad \text{as } t \to \infty.\tag{2.10}$$

Case (v) simple shear:

$$L(t) = \begin{pmatrix} 0 & K & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}, \quad K \neq 0.\tag{2.11}$$

Case (vi) simple shear with decaying planar dilatation/shear:

$$L(t) = \begin{pmatrix} 0 & K_2 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} + \frac{1}{t} \begin{pmatrix} 0 & K_1 K_3 & K_1 \\ 0 & 0 & 0 \\ 0 & K_3 & 1 \end{pmatrix} + O\left(\frac{1}{t^2}\right), \quad K_2 \neq 0. \quad (2.12)$$

Case (vii) combined orthogonal shear:

$$L(t) = \begin{pmatrix} 0 & K_3 & K_2 - tK_1 K_3 \\ 0 & 0 & K_1 \\ 0 & 0 & 0 \end{pmatrix}, \quad K_1 K_3 \neq 0. \quad (2.13)$$

Remark 2.1.   As we observed in [18] there are choices of $A \in M_{3\times 3}(\mathbb{R})$ for which $L(t)$ blows up in finite time, but we will restrict here to the case $\det(I + tA) > 0$ for all $t \geqslant 0$.

2.1. Hydrodynamical fields for homoenergetic solutions

We introduce the following quantities. The density ρ

$$\rho(t, x) = \int_{\mathbb{R}^3} f(t, x, v) \, dv, \quad (2.14)$$

the average velocity V at each point x and time t by means of

$$\rho(t, x) V(t, x) = \int_{\mathbb{R}^3} f(t, x, v) \, v \, dv. \quad (2.15)$$

and the internal energy ε (or temperature) at each point x and time t by means of

$$\rho(t, x) \varepsilon(t, x) = \int_{\mathbb{R}^3} f(t, x, v) (v - V(t, x))^2 dv. \quad (2.16)$$

We will denote as $c := v - V$ the random or peculiar velocity, namely the deviation of the velocity of a single particle from the average velocity. We define the stress tensor and the heat flux in terms of c and f as

$$M_{ij} = \int_{\mathbb{R}^3} c_i c_j f(t, x, v) \, dv, \quad i, j = 1, 2, 3 \quad (2.17)$$

$$q_i(t, x) = \int_{\mathbb{R}^3} c_i |c|^2 f(t, x, v) \, dv \quad i = 1, 2, 3. \quad (2.18)$$

The Boltzmann equation (1.3) implies the following not closed system of five scalar conservation laws (mass, momentum and kinetic energy). See for instance [9, 24].

$$\frac{\partial \rho}{\partial t} + \sum_{j=1}^{3} \frac{\partial}{\partial x_j}(\rho V_j) = 0; \quad (2.19)$$

$$\frac{\partial}{\partial t}(\rho V_i) + \sum_{j=1}^{3} \frac{\partial}{\partial x_j}(\rho V_i V_j + M_{ij}) = 0 \quad i = 1, 2, 3 \quad (2.20)$$

$$\frac{\partial}{\partial t}(\rho \varepsilon) + \sum_{j=1}^{3} \frac{\partial}{\partial x_j}\left(\rho \varepsilon V_j + q_j\right) + \sum_{i=1}^{3} \sum_{j=1}^{3} M_{ij} \frac{\partial V_i}{\partial x_j} = 0. \quad (2.21)$$

We now rewrite the quantities defined above in the case of homoenergetic flows (cf (2.1)). We can assume without loss of generality (see remark 2.2 below) that the class of homoenergetic solutions $g(t, w)$ we consider satisfies $\int_{\mathbb{R}^3} g(t, w) w \mathrm{d}w = 0$. Then, we have

$$\rho(t) = \int_{\mathbb{R}^3} g(t, w) \mathrm{d}w, \tag{2.22}$$

$$V(t, x) = \xi(x, t), \tag{2.23}$$

$$\rho(t) \varepsilon(t) = \frac{1}{2} \int_{\mathbb{R}^3} g(t, w) |w|^2 \mathrm{d}w, \tag{2.24}$$

and

$$M_{ij}(t) = \int_{\mathbb{R}^3} w_i w_j g \mathrm{d}w \quad i, j = 1, 2, 3 \tag{2.25}$$

$$q_i(t) = \frac{1}{2} \int_{\mathbb{R}^3} w_i |w|^2 g \mathrm{d}w \quad i = 1, 2, 3. \tag{2.26}$$

Therefore, the conservation laws (2.19)–(2.21) become

$$\frac{\partial}{\partial t} \rho(t) + \sum_{j=1}^{3} \frac{\partial}{\partial x_j} \left(\rho \xi_j \right) = 0; \tag{2.27}$$

$$\frac{\partial}{\partial t} (\rho(t) \xi_i) + \sum_{j=1}^{3} \frac{\partial}{\partial x_j} \left(\rho \xi_i \xi_j \right) = 0 \quad i = 1, 2, 3 \tag{2.28}$$

$$\frac{\partial}{\partial t} (\rho(t) \varepsilon) + \sum_{j=1}^{3} \frac{\partial}{\partial x_j} \left(\rho \varepsilon \xi_j \right) + \sum_{i=1}^{3} \sum_{j=1}^{3} M_{ij} \frac{\partial \xi_i}{\partial x_j} = 0. \tag{2.29}$$

We notice that the equation for the average velocity does not depend on the stress tensor and the equation for the internal energy does not contain the heat flux.

Using now (2.3), i.e. $\xi(t, x) = L(t) x + B(t)$, in (2.27)–(2.29) we obtain

$$\frac{\partial}{\partial t} \rho(t) + \rho(t) \operatorname{Tr}(L(t)) = 0; \tag{2.30}$$

$$\rho(t) \left(\frac{\partial \xi_i(t)}{\partial t} + \sum_{j=1}^{3} \xi_j \frac{\partial \xi_i(t)}{\partial x_j} \right) = 0 \quad i = 1, 2, 3 \tag{2.31}$$

$$\rho(t) \frac{\partial \varepsilon(t)}{\partial t} + \sum_{i=1}^{3} \sum_{j=1}^{3} M_{ij}(t) L_{ij}(t) = \rho(t) \frac{\partial \varepsilon(t)}{\partial t} + \operatorname{Tr}((ML)(t)) = 0, \tag{2.32}$$

where $\operatorname{Tr}(ML) = \int_{\mathbb{R}^3} w \cdot Lw \, g \, \mathrm{d}w$. We observe that (2.30) gives the evolution of the density in time, (2.31) holds due to (2.2) and (2.32) yields the evolution of the internal energy.

Notice that (2.30) implies

$$\rho(t) = \rho(0) \exp \left(-\int_0^t \operatorname{Tr}(L(s)) \, \mathrm{d}s \right). \tag{2.33}$$

which gives the evolution of the density in terms of the properties of the flow described by $L(t)$. On the contrary, we cannot compute the evolution of the internal energy $\varepsilon(t)$ without obtaining before some additional information concerning the velocity distribution function $g(t, w)$.

Remark 2.2. Multiplying (1.9) by w_k, for $k = 1, 2, 3$ and integrating with respect to w we obtain

$$\frac{\partial}{\partial t} \left(\int_{\mathbb{R}^3} g w_k \mathrm{d}w \right) + L_{k,j} \int_{\mathbb{R}^3} g w_j \mathrm{d}w + \mathrm{Tr}(L) \int_{\mathbb{R}^3} g w_k \mathrm{d}w = 0,$$

We can assume without loss of generality that $\int_{\mathbb{R}^3} g_0 w_k \mathrm{d}w = 0$ at $t = 0$ for $k = 1, 2, 3$ changing, if needed, the value of B_0. This implies $\int_{\mathbb{R}^3} g w_k \mathrm{d}w = 0$ for any $t > 0$.

3. Homoenergetic flows with hyperbolic-dominated behaviour for large $t \to \infty$

For some homoenergetic flows satisfying (1.9) and some choices of the homogeneity γ of the collision kernel B we can expect the hyperbolic term $-L(t) w \cdot \partial_w g$ to be much larger than the collision term $\mathbb{C}g(t, w)$ (cf (1.9)). The information that we have about those homoenergetic flows is much more fragmentary than the one obtained in the cases in which the collision terms are the dominant ones for large t (see [19]) or in the case in which the hyperbolic and collision terms have the same order of magnitude as $t \to \infty$ (see [18]). In the first case we have obtained that the asymptotics of the velocity distributions of the homoenergetic flows are given by Maxwellian distributions with time dependent temperatures, whose evolution in time is computed using suitable adaptations of the classical Hilbert expansions. In the second case, we have proved in [18] the existence of non Maxwellian self-similar solutions which describe the long time asymptotics of the particle distributions. Nevertheless, in both cases, there is a time dependent characteristic velocity $|w| \approx \ell(t)$ which characterizes the scale of velocities in which most of the particles of the system as well as the energy is contained at a given time. More precisely, this means that if we denote by $M(t), E(t)$ the mass and the energy of the system respectively, we have

$$M(t) \simeq \int_{\delta\ell(t) \leqslant |w| \leqslant \frac{1}{\delta}\ell(t)} g(t, w) \mathrm{d}w$$

and

$$E(t) \simeq \int_{\delta\ell(t) \leqslant |w| \leqslant \frac{1}{\delta}\ell(t)} |w|^2 g(t, w) \mathrm{d}w$$

for some $\delta > 0$ small enough.

　　In several of the cases dominated by the hyperbolic terms discussed in this section we will argue that such scale $\ell(t)$ containing most of the particles and the energy does not exist, or there is no single time-dependent velocity scale that characterizes both mass and energy as $t \to \infty$.

　　A feature that characterizes several of the homoenergetic flows dominated by hyperbolic terms is the fact that the collisions term, in spite of the fact that it is formally very small as $t \to \infty$, yields huge effects in the particle distributions. This feature can be understood in an intuitive manner in terms of the trajectories of the particles which are described by the Boltzmann equation in homoenergetic flows. During most of the time the dynamics of the particles is described by the hyperbolic flow, typically a shear flow, a dilatation flow or a combination
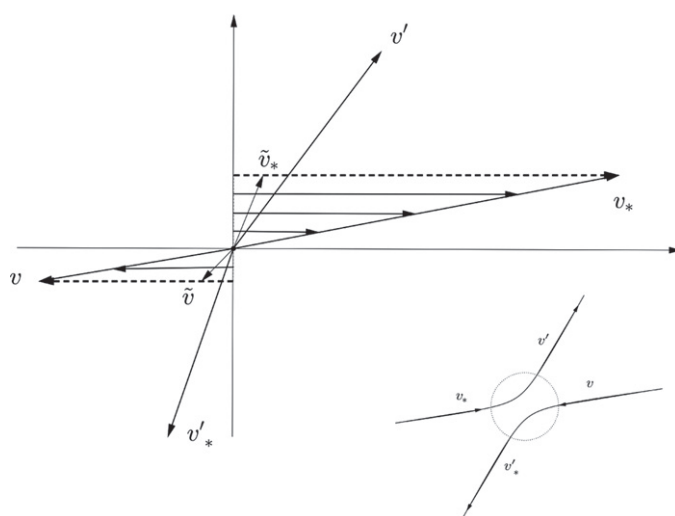
Figure 2. Increase of average velocity due to the combined effect of shear and collisions. The velocities $\tilde{v}, \tilde{v}_*$ are transformed into v, v_* by the shear. Then the collisions transform these velocities into v', v'_*.

of them. Rarely, the particle experiences a collision with other particles and this modifies drastically the direction of the motion of the particle. Then the particle velocity evolves again according to the hyperbolic flows and this results in an additional increase of the size of the velocities. Therefore the iteration of this process yields a huge increase of the average velocities and therefore of the 'temperature' of the system. Moreover, the effect of the collisions in the long time asymptotics of the particle distribution is huge in spite of the fact that they take place very rarely. See figure 2. This phenomenon will be studied in section 3.5 relying on the analysis of a collisional model simpler than the Boltzmann equation.

As discussed above the information that we have obtained so far for these flows with dominant hyperbolic terms is less detailed and more fragmentary than the one that we have obtained in the collision-dominated case. We will describe below a few examples of these flows and we will describe the dynamics of a simplified model which contains the combined effect explained above (simple shear during large times combined with rare collisions). Hopefully some of the ideas described in such simplified model might be useful to understand homoenergetic flows for the Boltzmann equation dominated by hyperbolic terms.

3.1. Homogeneous dilatation: frozen collisions

We recall that the homoenergetic flows (2.1) in the case of homogeneous dilatation (i.e. $L(t)$ given by (2.8)) have been studied in [21, 22]. We observe that in these flows the average dispersion of the velocity of the particles decreases as $\frac{1}{t}$ as $t \to \infty$, something that it is just due to the dilatation process of the gas with the collisions not having any meaningful effect on this fact. The long time asymptotics of the distribution then depends on the behaviour of the average time between collisions and this depends on the homogeneity of the collision kernel B which we denote as γ. As it has been seen in [19] if $\gamma \leqslant -2$ the effect of the collisions is relevant in the long time asymptotics and the velocity distribution converges to a Maxwellian distribution. If $\gamma > -2$, we will obtain the behaviour that we will denote as frozen

collisions as $t \to \infty$. Indeed, the effect of the isotropic dilatation is to reduce the average dispersion of the velocity of the molecules. Therefore, the effect of the collisions becomes negligible for large times and the particle distribution $g(t, w)$ converges asymptotically to a distribution $g_\infty(w)$ which depends on the initial particle distribution $g_0(w)$.

To be more precise, we consider the following equation which has been derived in subsection 4.2.4 in [19]

$$\partial_\tau G - \partial_\xi \cdot (\bar{\alpha}(\tau) \xi G) = \mathrm{e}^{-(2+\gamma)\tau} \mathbb{C} G(\xi) \tag{3.1}$$

where $|\bar{\alpha}(\tau)| \leqslant C \mathrm{e}^{-\tau}$ and G has been defined as

$$g(t, w) = t^3 G(\tau, \xi), \quad \xi = wt, \ \tau = \log(t). \tag{3.2}$$

where g is a solution to (1.9) with $L(t)$ given by (2.8).

Looking at the new time scale

$$\mathrm{d}s = \mathrm{e}^{-(2+\gamma)\tau} \mathrm{d}\tau$$

when $\gamma > -2$, we then have $(2 + \gamma) > 0$ and

$$s = \frac{1}{(2+\gamma)} \left(1 - \mathrm{e}^{-(2+\gamma)\tau} \right).$$

Therefore (3.1) becomes

$$\partial_s G - \partial_\xi \cdot (\kappa(s) \xi G) = \mathbb{C} G(\xi) \tag{3.3}$$

where s takes value in the interval $\left[0, \frac{1}{(2+\gamma)} \right)$ when τ takes value in $[0, \infty)$. Moreover, $\kappa(s)$ is bounded in the interval $0 \leqslant s \leqslant \frac{1}{(2+\gamma)}$. Therefore, in order to compute the asymptotic behaviour of the solutions of (3.1) as $\tau \to \infty$, we just need to compute the asymptotic behaviour of the solutions $G(s, w)$ of (3.3) as $s \to \frac{1}{(2+\gamma)}$. Therefore $G(s, w)$ does not converge to a Gaussian, but to a limit measure $G_\infty(\xi)$ which depends on the initial value $g_0(w)$. Therefore (3.2) implies that $g(w, t) \sim t^3 G_\infty(wt)$.

3.2. Cylindrical dilatation: frozen collisions

We now consider (1.9) choosing $L(t)$ as in (2.9) with $K = 0$. We obtain the following equation

$$\partial_t g - \frac{1}{t} \left(w_1 \partial_{w_1} + w_2 \partial_{w_2} \right) g = \int_{\mathbb{R}^3} \mathrm{d}w_* \int_{S^2} \mathrm{d}\omega \, B \left(\omega, |w - w_*| \right) \left[g' g'_* - g_* g \right] \tag{3.4}$$

when the kernel has homogeneity $\gamma > -2$. We remark that the case of Maxwellian molecules (i.e. $\gamma = 0$) has been considered by Galkin in [15] where formulae for the second order moments of the velocity distribution have been computed using hypergeometric functions.

In order to rewrite the equation above in divergence form we use the change of variables: $g(t, w) = \frac{1}{t^2} G(t, w)$, $\log(t) = \tau$. Then, (3.4) becomes

$$\partial_\tau G - \partial_w \cdot (D w G) = \mathrm{e}^{-\tau} \mathbb{C} G, \quad \text{with} \quad D = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 0 \end{pmatrix}. \tag{3.5}$$

We study under which conditions we can obtain solutions of (3.5) whose behaviour is determined for $\tau \to \infty$ by the terms on the left-hand side. Suppose that we replace the collision term $e^{-\tau}\mathbb{C}G$ on the right-hand side of (3.5) by 0. Then, the solutions by the method of characteristics of the corresponding equation would be given by

$$G(\tau, w) = e^{2\tau}G_0(e^{\tau}w_1, e^{\tau}w_2, w_3) \tag{3.6}$$

where G_0 is the initial distribution which we assume to be sufficiently smooth and exponentially decaying as $|w| \to \infty$.

We now check that the collision terms obtained with a function G of the form (3.6) will not modify the form of the solutions obtained by the method of characteristics as $\tau \to \infty$. The *rate of collisions* is given by

$$e^{-\tau}\int_{\mathbb{R}^3}\mathrm{d}w_*\int_{S^2}\mathrm{d}\omega B\left(n\cdot\omega, |w - w_*|\right)G(\tau, w_*)$$

which can be estimated as

$$Ce^{-\tau}\int_{\mathbb{R}^3}\mathrm{d}w_*|w - w_*|^{\gamma}G(\tau, w_*). \tag{3.7}$$

We estimate the supremum in w of (3.7). If we assume that G has the form (3.6) we can estimate this supremum, for $|w| \leqslant C$, by the value at $w = 0$. We then need to estimate

$$Ce^{-\tau}\int_{\mathbb{R}^3}\mathrm{d}w_*|w_*|^{\gamma}G(\tau, w_*). \tag{3.8}$$

Due to the assumption we did on the initial distribution G_0 it follows that G as well as the moment $\int_{\mathbb{R}^3}\mathrm{d}w_*|w_*|^{|\gamma|}G(w_*, \tau) < \infty$ for each $\tau \geqslant 0$. We consider separately the cases $\gamma \geqslant 0$ and $\gamma < 0$. If $\gamma \geqslant 0$ and G has the form (3.6) we obtain that (3.8) is bounded by $Ce^{-\tau}$, since the mass of G is concentrated in the region where $|w_*|$ is bounded. Therefore, the rate of collisions decreases exponentially as $\tau \to \infty$ and we can expect the asymptotics (3.6) for G as $\tau \to \infty$. Suppose now that $-2 < \gamma < 0$ and that G has the form (3.6). We then obtain, using the change of variables $\xi_1 = e^{\tau}w_1, \xi_2 = e^{\tau}w_2$, the following estimate for (3.8)

$$Ce^{-\tau}\int_{\mathbb{R}^3}\mathrm{d}\xi_1\mathrm{d}\xi_2\mathrm{d}w_3\left[e^{-2\tau}\left((\xi_1)^2 + (\xi_2)^2\right) + (w_3)^2\right]^{\frac{\gamma}{2}}G_0(\xi_1, \xi_2, w_3).$$

We assume that G_0 satisfies (3.6) and contains most of its mass in the region $|\xi_1| + |\xi_2| + |w_3| \leqslant C$. Performing then the change of variables $w_3 = e^{-\tau}\eta|\xi|$ with $\xi = (\xi_1, \xi_2) \in \mathbb{R}^2$, we obtain an estimate with the form

$$Ce^{-(2-|\gamma|)\tau}\int_{B_A(0)}\mathrm{d}\xi|\xi|^{1-|\gamma|}\int_{-\frac{Ae^{\tau}}{|\xi|}}^{\frac{Ae^{\tau}}{|\xi|}}\frac{\mathrm{d}\eta}{\left[1 + \eta^2\right]^{\frac{|\gamma|}{2}}}$$

where $A > 0$.

We now have two possibilities. If $1 < |\gamma| < 2$, $\gamma < 0$, the integral above is bounded by $Ce^{-(2-|\gamma|)\tau}$. If $|\gamma| < 1$, $\gamma < 0$, we obtain the estimate

$$Ce^{-\tau}\int_{B_A(0)}\mathrm{d}\xi \leqslant Ce^{-\tau}.$$

If $|\gamma| = 1$ we would obtain the estimate $C\tau e^{-\tau}$ with similar arguments. Summarizing, if $\gamma > -2$ the collision rate decreases exponentially and we can expect to have an asymptotics for G given by

$$G(\tau, w) = e^{2\tau} G_\infty(e^\tau w_1, e^\tau w_2, w_3) \tag{3.9}$$

where G_∞ would depend on G_0. Thus, in the original variables we obtain

$$g(t, w) \sim G_\infty(tw_1, tw_2, w_3).$$

Remark 3.1. It is interesting to remark that in [19] we have obtained that in the case of cylindrical dilatation with kernels B with homogeneity $\gamma < -\frac{3}{2}$ there are homoenergetic solutions for the Boltzmann equation described by means of Hilbert expansions and behaving like a Maxwellian distribution with decreasing temperature. On the other hand we have obtained in this subsection that a possible asymptotics of the homoenergetic solutions for the Boltzmann equation is given by (3.9) if $\gamma > -2$. The remarkable fact is that there is a non empty interval of homogeneities $\gamma \in \left(-2, -\frac{3}{2}\right)$ for which both asymptotics are possible. This suggests that the homoenergetic solutions of the Boltzmann equation can have different behaviours depending on the choice of initial data G_0 if $\gamma \in \left(-2, -\frac{3}{2}\right)$. In one of the asymptotics the effect of the collisions would be the dominant effect, while in the other one, the collisions would have a negligible effect for large times. This is a remarkable phenomenon which deserves a more detailed analysis, nonetheless we will not continue with the study of this case in this paper.

3.3. Simple shear. Frozen collisions for $\gamma < -1$

We consider homoenergetic flows (1.9) with $L(t)$ as in (2.11). Then g satisfies:

$$\partial_t g - K w_2 \partial_{w_1} g = \mathbb{C}g(w). \tag{3.10}$$

We will show that if the homogeneity of the collision kernel B is smaller than -1 there exist solutions of (3.10) for which the contribution of the collision term $\mathbb{C}g(w)$ is negligible as $t \to \infty$. For such solutions, a given particle would not collide with any other for large times, and we might expect to have w_2 approximately constant and w_1 increasing linearly in t. This suggests to look for solutions with the form

$$g(t, w) = \frac{1}{t} G(\tau, \xi) \ , \ \tau = \log(t), \ \xi_1 = \frac{w_1}{t}, \ \xi_j = w_j \text{ if } j = 2, 3. \tag{3.11}$$

Then, using the homogeneity of the kernel, we obtain that G satisfies

$$\partial_\tau G - \partial_\xi \cdot \left([(\xi_1 + K\xi_2) e_1] G \right) = e^{(1+\gamma)\tau} \mathbb{C}G(\xi). \tag{3.12}$$

Notice that the collision kernel has been also rescaled, due to the lack of isotropy of the change of variables (3.11).

The long time asymptotics of the hyperbolic equation obtained putting the right-hand side equal to zero in (3.12) is much dependent on the regularity properties of the initial data $G_0(\xi)$. We will assume for the sake of simplicity that $G_0 \in C^2$. The solution of the corresponding hyperbolic equation follows using the method of characteristics

$$G(\tau, \xi) = e^\tau G_0 \left(\xi_1 e^\tau + K\xi_2 \left(e^\tau - 1\right), \xi_2, \xi_3\right),$$

$$g(t, w) = t\, G_0 \left(w_1 + Kw_2 \left(t - 1\right), w_2, w_3\right). \tag{3.13}$$

Suppose that G_0 is compactly supported or decreases sufficiently fast as $|w| \to \infty$. Then, integrating with respect to ξ against a smooth test function we obtain

$$G(\tau, \xi) \rightharpoonup \left[\int_{-\infty}^{\infty} G_0\left(\eta, \xi_2, \xi_3\right) d\eta\right] \delta\left(\xi_1 + K\xi_2\right) \text{ as } \tau \to \infty. \tag{3.14}$$

If $\gamma < -1$ it would follow that the contribution of the collision term $e^{(1+\gamma)\tau} \mathbb{C} G(\xi)$ decreases exponentially as $\tau \to \infty$ and it yields a negligible contribution as $\tau \to \infty$. In this case the effect of the collisions becomes frozen for large times. The rigorous proof of the smallness of this term would require some careful analysis of the collision term which will not be made in detail in this paper. The intuitive idea behind the convergence (3.14) is that collisions, for long times, take place so rarely that become negligible.

3.4. Combined shear in orthogonal directions

3.4.1. Derivation of a system of ODEs for the second order moments. We now consider the homoenergetic flows (1.9) with $L(t)$ as in (2.13). Then g solves

$$\partial_t g - \left[K_3 w_2 + \left(K_2 - tK_1 K_3\right) w_3\right] \partial_{w_1} g - K_1 w_3 \partial_{w_2} g = \mathbb{C} g(w). \tag{3.15}$$

It readily follows that $\partial_t \left(\int_{\mathbb{R}^3} g(t, dw)\right) = 0$. On the other hand, as we have seen in [19], for homogeneity $\gamma > 0$ the asymptotic behaviour of solutions of (3.15) is given by Maxwellian distributions with time dependent temperature, obtained by means of suitable Hilbert expansions. Such expansions do not exist for $\gamma < 0$. Therefore we can expect the critical value of the homogeneity at $\gamma = 0$. We can obtain some insight about the asymptotics of g from the asymptotics of the second moments $M_{j,k} = \int_{\mathbb{R}^3} w_j w_k g(t, dw)$. The asymptotic formulae we obtain for the moments will rule out the possibility of self-similar behaviour.

We consider the evolution equation for the second moments $M_{j,k} = \int_{\mathbb{R}^3} w_j w_k g(t, dw)$. From (3.15) at $\gamma = 0$ a straightforward computation yields

$$\frac{dM_{j,k}}{dt} = K_3 \delta_{j,1} M_{k,2} + \left[\left(K_2 - tK_1 K_3\right) \delta_{j,1} + K_1 \delta_{j,2}\right] M_{k,3} + + K_3 \delta_{k,1} M_{j,2}$$

$$+ \left[\left(K_2 - tK_1 K_3\right) \delta_{k,1} + K_1 \delta_{k,2}\right] M_{j,3} - 2b\left(M_{j,k} - m\delta_{j,k}\right) \tag{3.16}$$

for $j, k = 1, 2, 3$, $M_{j,k} = M_{k,j}$, $m = \frac{1}{3}\left(M_{1,1} + M_{2,2} + M_{3,3}\right)$ and

$$b = 3\pi \int_{-1}^{1} B(x) x^2 \left(1 - x^2\right) dx > 0. \tag{3.17}$$

The system of equations (3.16) is linear. Due to the assumption $K_1 K_3 \neq 0$ there is a linear increase of the terms on the right-hand side of this system. It is then natural to derive asymptotic formulae for its solutions using a WKB method (see for instance [4]). Indeed, these methods are applicable for linear problems for which the terms multiplying the higher order derivatives are asymptotically smaller than the terms multiplying lower order derivatives. We will derive asymptotic formulae for six linearly independent solutions of (3.16). We make

the ansatz $M_{j,k} \sim \gamma_{j,k}e^S$ where $\gamma_{j,k}$ are functions behaving like power laws (perhaps containing logarithmic corrections) and S behaves like a polynomial. We first need to compute the leading order of this asymptotic expansion. To this end we rewrite (3.16) neglecting the contribution of the term K_2 in $(K_2 - tK_1K_3)$ since it is lower order. With this approximation we have

$$\frac{dM_{1,1}}{dt} = -2K_3M_{1,2} + 2tK_1K_3M_{1,3} - 2b\left(M_{1,1} - m\right)$$

$$\frac{dM_{1,2}}{dt} = -K_3M_{2,2} + tK_1K_3M_{2,3} - K_1M_{1,3} - 2bM_{1,2}$$

$$\frac{dM_{1,3}}{dt} = -K_3M_{2,3} + tK_1K_3M_{3,3} - 2bM_{1,3}$$

$$\frac{dM_{2,2}}{dt} = -2K_1M_{2,3} - 2b\left(M_{2,2} - m\right)$$

$$\frac{dM_{2,3}}{dt} = -K_1M_{3,3} - 2bM_{2,3}$$

$$\frac{dM_{3,3}}{dt} = -2b\left(M_{3,3} - m\right)$$

$$m = \frac{1}{3}\left(M_{1,1} + M_{2,2} + M_{3,3}\right). \tag{3.18}$$

3.4.2. Computations of the asymptotics for the second order moments. We can determine the exponential behaviour of the coefficients using a graphic procedure. To this end we represent each of the variables $M_{j,k}$ as the nodes of a graph. (See figure 3). We then include in the graph a directed edge connecting each of the nodes appearing on the right-hand side of (3.18) (including those on m) with the variable appearing under the derivative on the right-hand side. We will assume that the directed edges are of two different types, namely thick and thin. More precisely, we add an edge of type thin if the term appearing on the right-hand side is multiplied by a constant, and we will assume that the edge is thick if the corresponding variable on the right-hand side of (3.18) is proportional to t. Suppose that $M_{j,k}$ is a variable at the origin of one directed edge on the graph and $M_{r,s}$ is a variable at the end of one of such directed edges. Then, the structure of the equations (3.18) implies the following rule to determine the structure of the algebraic factors $\gamma_{j,k}$

$$c_{j,k}\gamma_{j,k} = (\partial_t S)\,\gamma_{r,s} \text{ if the directed edge is thin,}$$
$$c_{j,k}t\gamma_{j,k} = (\partial_t S)\,\gamma_{r,s} \text{ if the directed edge is thick,} \tag{3.19}$$

where $c_{j,k}$ is the multiplicative constant in front of the function $M_{j,k}$ in (3.18).

We then look for circuits in the graph associated to the set of equations (3.18) having the shortest length and the largest number of thick lines. More precisely, for any circuit connecting a node $M_{j,k}$ with itself, the set of rules (3.19) implies that

$$C_0\gamma_{j,k}t^T = (\partial_t S)^L\gamma_{j,k} \tag{3.20}$$

where L is the total number of edges of the circuit and T is the number of thick lines on it. The constant C_0 is just the product of the coefficients $c_{j,k}$ in the cycle.
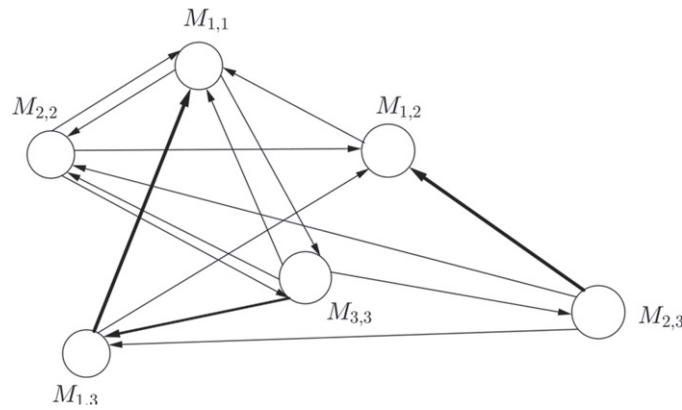
Figure 3. The graphic procedure for the WKB method.

We select the circuits for which the number $\frac{T}{L}$ is the largest. Notice that by construction $\frac{T}{L} < 1$. Then, the consistency of (3.20) yields

$$S \sim \frac{|C_0|^{\frac{1}{L}}\omega}{1+\frac{T}{L}} t^{1+\frac{T}{L}} \text{ as } t \to \infty \tag{3.21}$$

where ω is one of the L complex roots of the equation

$$\omega^L = \text{sgn}\,(C_0)\,.$$

The asymptotics (3.21) yields the leading asymptotic behaviour of L independent solutions of (3.18). We can derive asymptotic formulae for additional solutions removing the nodes which are at the basis of the thick lines contained in the cycles yielding contributions to the asymptotics (3.21), if needed. In such a case, in order to obtain the asymptotics of the additional solutions, we obtain formulae relating some of the asymptotic variables $M_{j,k}$ removing the derivatives in the equations associated to the thick lines removed and finding then asymptotic relations between the corresponding right-hand sides of the resulting equations.

We apply the method explained above to the equations (3.18). The cycle yielding the smallest value of $\frac{T}{L}$ is

$$M_{1,1} \to M_{3,3} \to M_{1,3} \to M_{1,1}. \tag{3.22}$$

Then, we obtain to the leading order

$$(S_t)^3 \sim \frac{4b}{3}(tK_1K_3)^2 \text{ as } t \to \infty$$

whence

$$S \sim \frac{3}{5}\left(\frac{4b}{3}\right)^{\frac{1}{3}}(K_1K_3)^{\frac{2}{3}}\omega t^{\frac{5}{3}} \text{ as } t \to \infty \tag{3.23}$$

where $\omega^3 = 1$. We are interested in the value of ω yielding the fastest growth of the solutions, i.e. $\omega = 1$.

We compute the remaining long time asymptotics of (3.18) as a consistency test. We will impose that $\frac{dM_{3,3}}{dt} = \frac{dM_{1,3}}{dt} = \frac{dM_{1,1}}{dt} = 0$ (or, more precisely, that the contributions of these derivatives yield subdominant terms). We then need to solve the equations

$$\frac{dM_{1,2}}{dt} = -K_3 M_{2,2} + tK_1 K_3 M_{2,3} - K_1 M_{1,3} - 2bM_{1,2}$$

$$\frac{dM_{2,2}}{dt} = -2K_1 M_{2,3} - 2b\left(M_{2,2} - m\right)$$

$$\frac{dM_{2,3}}{dt} = -K_1 M_{3,3} - 2bM_{2,3} \tag{3.24}$$

$$m = \frac{1}{3}\left(M_{1,1} + M_{2,2} + M_{3,3}\right)$$

with the constraints

$$0 = -2K_3 M_{1,2} + 2tK_1 K_3 M_{1,3} - 2b\left(M_{1,1} - m\right)$$

$$0 = -K_3 M_{2,3} + tK_1 K_3 M_{3,3} - 2bM_{1,3}$$

$$0 = -2b\left(M_{3,3} - m\right).$$

Using the last equation we can write

$$\left(M_{1,1} - m\right) = \left(M_{1,1} - M_{3,3}\right) + \left(M_{3,3} - m\right) = \left(M_{1,1} - M_{3,3}\right),$$

whence

$$0 = -2K_3 M_{1,2} + 2tK_1 K_3 M_{1,3} - 2b\left(M_{1,1} - M_{3,3}\right)$$

$$0 = -K_3 M_{2,3} + tK_1 K_3 M_{3,3} - 2bM_{1,3}$$

$$0 = 2M_{3,3} - M_{1,1} - M_{2,2}. \tag{3.25}$$

Neglecting subdominant terms and using the first equation we obtain

$$M_{1,3} = \frac{K_3 M_{1,2} + bM_{1,1}}{K_1 K_3} \frac{1}{t}. \tag{3.26}$$

Plugging this into the second equation of (3.25) we obtain

$$M_{3,3} = \frac{M_{2,3}}{K_1}\frac{1}{t} + \frac{2b\left(K_3 M_{1,2} + bM_{1,1}\right)}{\left(K_1 K_3\right)^2}\frac{1}{t^2}. \tag{3.27}$$

Notice that we have neglected the term $-\frac{bM_{3,3}}{K_1 K_3 t}$ in (3.26). This would result in a term of order $O\left(\frac{M_{3,3}}{t^3}\right)$ in (3.27) which is lower order $M_{3,3}$ compared to the term on the left of (3.27). Therefore, we would neglect it. Inserting now this formula into the last equation of (3.25) and neglecting small terms we obtain

$$\frac{2M_{2,3}}{K_1}\frac{1}{t} + \frac{4b\left(K_3 M_{1,2} + bM_{1,1}\right)}{\left(K_1 K_3\right)^2}\frac{1}{t^2} - M_{1,1} - M_{2,2} = 0$$

$$M_{1,1} = \frac{2M_{2,3}}{K_1}\frac{1}{t} + \frac{4bK_3 M_{1,2}}{\left(K_1 K_3\right)^2}\frac{1}{t^2} - M_{2,2}. \tag{3.28}$$

Using this into (3.26), (3.27) and neglecting small terms we get

$$M_{1,3} = \left(\frac{M_{1,2}}{K_1} \frac{1}{t} + \frac{2bM_{2,3}}{(K_1)^2 K_3} \frac{1}{t^2} - \frac{bM_{2,2}}{K_1 K_3} \frac{1}{t} \right) \tag{3.29}$$

$$M_{3,3} = \frac{M_{2,3}}{K_1} \frac{1}{t} + \frac{2bK_3 M_{1,2}}{(K_1 K_3)^2} \frac{1}{t^2} + \frac{2b^2 M_{2,2}}{(K_1 K_3)^2} \frac{1}{t^2}. \tag{3.30}$$

We can now use (3.28)–(3.30) to eliminate $M_{1,1}, M_{1,3}, M_{3,3}$ from (3.24). Eliminating subdominant terms we obtain

$$\frac{\mathrm{d}M_{1,2}}{\mathrm{d}t} = -K_3 M_{2,2} + tK_1 K_3 M_{2,3} - 2bM_{1,2}$$

$$\frac{\mathrm{d}M_{2,2}}{\mathrm{d}t} = -2K_1 M_{2,3} - 2bM_{2,2} + \frac{4b^2 K_3 M_{1,2}}{3(K_1 K_3)^2} \frac{1}{t^2}$$

$$\frac{\mathrm{d}M_{2,3}}{\mathrm{d}t} = \frac{2bK_3 M_{1,2}}{(K_1 K_3)^2} \frac{1}{t^2} - K_1 \frac{2b^2 M_{2,2}}{(K_1 K_3)^2} \frac{1}{t^2} - 2bM_{2,3}. \tag{3.31}$$

These equations have three independent solutions which decrease exponentially. More precisely, the asymptotics of these solutions can be computed with the same type of arguments used above and the conclusion is the existence of three independent solutions having the following asymptotics. Two of them behave like:

$$M_{j,k} = \exp\left(-2bt \pm \sqrt{\frac{2b}{K_1}} t (1 + \varepsilon_{j,k}(t)) \right) \quad \text{for} \quad (j,k) \in \{(1,2),(2,2),(2,3)\} \quad \text{as} \quad t \to \infty \tag{3.32}$$

where $\varepsilon_{j,k}(t) \to 0$ as $t \to \infty$, and the third one behaves like:

$$M_{j,k} = \mathrm{e}^{-2bt} \gamma_{j,k} \quad \text{for } (j,k) \in \{(2,3)\} \, (j,k) \in \{(1,2),(2,2),(2,3)\} \quad \text{as } t \to \infty \tag{3.33}$$

where $\gamma_{j,k}$ are such that $\gamma_{2,2} = \frac{1}{t^2}$, $\gamma_{2,3} \sim \frac{1}{K_1 t} \gamma_{2,2}$, $\gamma_{1,2} \sim \frac{K_1 b}{K_3} \gamma_{2,2}$ as $t \to \infty$. This means that we have three additional independent solutions to the ones having the asymptotics (3.23), but we will not give more details about them in what follows since we will not use them later.

The relevant asymptotics, which yields the behaviour of the functions $M_{j,k}$ for generic initial data is the one yielding $S \sim \frac{3}{5} \left(\frac{4b}{3} \right)^{\frac{1}{3}} (K_1 K_3)^{\frac{2}{3}} t^{\frac{5}{3}}$ as $t \to \infty$. We can compute additional terms in the asymptotics of the solutions $M_{j,k}$.

To this end we introduce the change of variables

$$M_{j,k} = \mathrm{e}^{S_0 + H_{j,k}} \,, \quad S_0 = \frac{3}{5} \left(\frac{4b}{3} \right)^{\frac{1}{3}} (K_1 K_3)^{\frac{2}{3}} t^{\frac{5}{3}} \tag{3.34}$$

where the behaviour of the functions $H_{j,k}$ must be computed. By assumption $|H_{j,k}| \ll t^{\frac{5}{3}}$ as $t \to \infty$. We will assume also that terms in the differential equations which are not associated to the nodes appearing in the cycle (3.22) yield negligible contributions. We will check

then '*a posteriori*' that these assumptions are satisfied in the derived asymptotic formulae for $H_{j,k}$. We remark that the leading order asymptotics derived above imply

$$e^{H_{1,3}-H_{1,1}} \sim \frac{\partial_t S_0}{2tK_1K_3}, \quad e^{H_{3,3}-H_{1,3}} \sim \frac{\partial_t S_0}{tK_1K_3}, \quad e^{H_{1,1}-H_{3,3}} \sim \frac{3\partial_t S_0}{2b}. \quad (3.35)$$

On the other hand, plugging (3.34) into (3.18) we obtain

$$\partial_t S_0 + \partial_t H_{1,1} = 2tK_1K_3 e^{H_{1,3}-H_{1,1}} - 2K_3 e^{H_{1,2}-H_{1,1}} - K_2 e^{H_{1,3}-H_{1,1}}$$

$$- \frac{2b}{3}\left(2 - e^{H_{2,2}-H_{1,1}} - e^{H_{3,3}-H_{1,1}}\right)$$

$$\partial_t S_0 + \partial_t H_{1,2} = -K_3 e^{H_{2,2}-H_{1,2}} + (tK_1K_3 - K_2)\,e^{H_{2,3}-H_{1,2}} - K_1 e^{H_{1,3}-H_{1,2}} - 2b$$

$$\partial_t S_0 + \partial_t H_{1,3} = tK_1K_3 e^{H_{3,3}-H_{1,3}} - K_3 e^{H_{2,3}-H_{1,3}} - K_2 e^{H_{3,3}-H_{1,3}} - 2b$$

$$\partial_t S_0 + \partial_t H_{2,2} = -2K_1 e^{H_{2,3}-H_{2,2}} - \frac{2b}{3}\left(2 - e^{H_{1,1}-H_{2,2}} - e^{H_{3,3}-H_{2,2}}\right)$$

$$\partial_t S_0 + \partial_t H_{2,3} = -K_1 e^{H_{3,3}-H_{2,3}} - 2b$$

$$\partial_t S_0 + \partial_t H_{3,3} = \frac{2b}{3}e^{H_{1,1}-H_{3,3}} - \frac{2b}{3}\left(2 - e^{H_{2,2}-H_{3,3}}\right). \quad (3.36)$$

We first derive information about the asymptotics of the variables not contained in the cycle (3.22). The equations for the variables $H_{1,2}, H_{2,2}, H_{2,3}$ yield, neglecting lower order terms,

$$\partial_t S_0 = -K_3 e^{H_{2,2}-H_{1,2}} + tK_1K_3 e^{H_{2,3}-H_{1,2}} - K_1 e^{H_{1,3}-H_{1,2}}$$

$$\partial_t S_0 = -2K_1 e^{H_{2,3}-H_{2,2}} + \frac{2b}{3}e^{H_{1,1}-H_{2,2}} + \frac{2b}{3}e^{H_{3,3}-H_{2,2}}$$

$$\partial_t S_0 = -K_1 e^{H_{3,3}-H_{2,3}}.$$

We can eliminate from these equations the variables $H_{1,3}, H_{3,3}$ using (3.35) whence, after neglecting small order terms and using that $\partial_t S_0$ scales like $t^{\frac{2}{3}}$

$$\partial_t S_0 = -K_3 e^{H_{2,2}-H_{1,2}} + tK_1K_3 e^{H_{2,3}-H_{1,2}} - \frac{\partial_t S_0}{2K_3 t}e^{H_{1,1}-H_{1,2}}$$

$$\partial_t S_0 = -2K_1 e^{H_{2,3}-H_{2,2}} + \frac{2b}{3}e^{H_{1,1}-H_{2,2}}$$

$$1 = -\frac{1}{2tK_3}e^{H_{1,1}-H_{2,3}}.$$

We can then write all the differences of functions $H_{j,k}$ in terms of differences $(H_{1,2} - H_{1,1})$, $(H_{2,2} - H_{1,1})$ and $(H_{2,3} - H_{1,1})$. Then, neglecting small terms as $t \to \infty$, we obtain

$$\partial_t S_0 = -K_3 e^{H_{1,1}-H_{1,2}}e^{H_{2,2}-H_{1,1}} - \frac{K_1}{2}e^{H_{1,1}-H_{1,2}}$$

$$e^{H_{1,1}-H_{2,2}} = \frac{3}{2b}\partial_t S_0 \ , \quad e^{H_{1,1}-H_{2,3}} = -2K_3 t$$

whence, after some computations,

$$e^{H_{1,1}-H_{2,3}} = -2K_3 t \,, \quad e^{H_{1,1}-H_{2,2}} = \frac{3}{2b}\partial_t S_0 \,, \quad e^{H_{1,1}-H_{1,2}} = -\frac{3}{2bK_3}\left(1 + \frac{3K_1}{4b}\right)(\partial_t S_0)^2.$$

(3.37)

Notice that the three functions $e^{H_{2,3}}$, $e^{H_{2,2}}$, $e^{H_{1,2}}$ are smaller than $e^{H_{1,1}}$ as $t \to \infty$. Notice that some of these functions can be negative, and therefore the corresponding function $H_{j,k}$ would have an additive complex factor $i\pi$.

We now compute the asymptotics of the functions $H_{1,1}, H_{1,3}, H_{3,3}$. Using the corresponding equations for the derivatives of these variables in (3.36) and eliminating the variables $H_{1,2}, H_{2,2}, H_{2,3}$ using (3.37) and neglecting small terms we obtain

$$\partial_t S_0 + \partial_t H_{1,1} = 2tK_1K_3 e^{H_{1,3}-H_{1,1}} + \frac{2b}{3}e^{H_{3,3}-H_{1,1}} - K_2 e^{H_{1,3}-H_{1,1}} - \frac{4b}{3}$$

$$\partial_t S_0 + \partial_t H_{1,3} = tK_1K_3 e^{H_{3,3}-H_{1,3}} - K_2 e^{H_{3,3}-H_{1,3}} + \frac{1}{2t}e^{H_{1,1}-H_{1,3}} - 2b$$

$$\partial_t S_0 + \partial_t H_{3,3} = \frac{2b}{3}e^{H_{1,1}-H_{3,3}} - \frac{4b}{3} + \frac{4b^2}{9}\frac{1}{\partial_t S_0}e^{H_{1,1}-H_{3,3}}.$$

Using (3.35) to approximate the corrective exponential terms in these equations we obtain

$$\partial_t S_0 + \partial_t H_{1,1} = 2tK_1K_3 e^{H_{1,3}-H_{1,1}} - \frac{4b}{3}$$

$$\partial_t S_0 + \partial_t H_{1,3} = tK_1K_3 e^{H_{3,3}-H_{1,3}} - 2b$$

$$\partial_t S_0 + \partial_t H_{3,3} = \frac{2b}{3}e^{H_{1,1}-H_{3,3}} - \frac{2b}{3}.$$

Multiplying these equations, using $|\partial_t H_{j,k}| \ll \partial_t S_0$ and keeping the leading order terms (using again (3.35) to approximate the exponential terms on the right-hand side) we get

$$\frac{\partial_t H_{1,1}}{\partial_t S_0} + \frac{\partial_t H_{1,3}}{\partial_t S_0} + \frac{\partial_t H_{3,3}}{\partial_t S_0} \sim -\left(\frac{4b}{3} + 2b + \frac{2b}{3}\right)\frac{1}{\partial_t S_0} = -\frac{4b}{\partial_t S_0}$$

whence, taking into account also that due to (3.35) we have $H_{1,1} \sim H_{1,3} \sim H_{3,3}$ as $t \to \infty$, it follows, to the leading order

$$H_{1,1} \sim H_{1,3} \sim H_{3,3} \sim -\frac{4b}{3}t \text{ as } t \to \infty.$$

We have thus obtained

$$S \sim \frac{3}{5}\left(\frac{4b}{3}\right)^{\frac{1}{3}}(K_1K_3)^{\frac{2}{3}}t^{\frac{5}{3}} - \frac{4b}{3}t \quad \text{as } t \to \infty.$$

(3.38)

3.4.3. The asymptotics of $M_{j,k}$ are not compatible with the self-similar behaviour for the velocity distribution. We now analyse if the asymptotics (3.38) is consistent with some of the self-similar behaviours described in [18], section 5. The asymptotics (3.38) for the tensor of second

moments $M_{j,k}$, combined with the mass conservation property, suggests the following long time behaviour for the solutions of (3.15)

$$g(t,w) = \frac{1}{(\lambda(t))^3}\Phi(\xi), \quad \xi = \frac{w}{\lambda(t)} \tag{3.39}$$

with

$$\log(\lambda(t)) \sim \frac{3}{10}\left(\frac{4b}{3}\right)^{\frac{1}{3}}(K_1 K_3)^{\frac{2}{3}}t^{\frac{5}{3}} \quad \text{as } t \to \infty.$$

Plugging (3.39) into (3.15) and keeping the leading order terms we obtain the following equation for Φ

$$-\frac{\partial_t \lambda}{\lambda}\Phi - [K_3\xi_2 + (K_2 - tK_1 K_3)\xi_3]\partial_{\xi_1}\Phi - K_1\xi_3\partial_{\xi_2}\Phi = \mathbb{C}\Phi(\xi).$$

Since $\frac{\partial_t \lambda}{\lambda} \sim \frac{1}{2}\left(\frac{4b}{3}\right)^{\frac{1}{3}}(K_1 K_3)^{\frac{2}{3}}t^{\frac{2}{3}}$ as $t \to \infty$ it is not possible to have a balance between the terms $\frac{\partial_t \lambda}{\lambda}\Phi(\xi)$ and $(K_1 K_3 t)\xi_3\partial_{\xi_1}\Phi$ unless $\partial_{\xi_1}\Phi \to 0$ as $t \to \infty$. In that case Φ would be approximately independent on ξ_1 at least for a large set of values and this would be incompatible with g having finite mass. Therefore, the long time asymptotics of the solutions of (3.15) cannot be described by a self-similar velocity distribution at least with the simple structure in (3.39).

3.5. A simple model with the hyperbolic terms much larger than the collision terms but yielding infinitely many collisions for long times

3.5.1. Description of the model. We have seen in some of the previous examples, that for some choices of the matrices $L(t)$ and some homogeneities of the kernels B the collision term becomes much smaller than the hyperbolic terms associated to the term $L(t)$. However, these collisions might yield huge deformations in the particle distribution. In this subsection we consider a simplified model inspired by the dynamics of the homoenergetic flows in the case of simple shear (cf (2.11)). We have seen in subsection 5.1 in [18] that in this case, if the homogeneity $\gamma = 0$, there are self-similar solutions for the particle velocities. If $\gamma > 0$ we have obtained in [19] a long time asymptotics described by a Maxwellian distribution with temperature increasing in time as a power law. In section 3.3 we have seen that for $\gamma < -1$ the average velocity of the particles increases due to the shear, but therefore the collisions become so small that they yield a negligible effect as $t \to \infty$. If $\gamma \in [-1,0)$ the description of the particle distribution seems more involved.

The main difficulty to describe the distribution of particles in the case of simple shear and $\gamma \in [-1,0)$ is the following. The shear is the dominant effect and it tends to yield a very elongated particle distribution, analogous to the one obtained for the case $\gamma < -1$ (cf (3.13), (3.14)). However, in the case $\gamma < -1$ the collision rate decreases very quickly as $t \to \infty$ and a given particle eventually does not experience any collision for long times. On the contrary, if $\gamma \in [-1,0)$ the collision rate becomes small as $t \to \infty$, but each particle experiences infinitely many collisions for long times, although increasingly spaced in time. The difficulty is that the collision rule (1.4), (1.5) implies that the collision between two particles whose velocities are in a distribution much elongated along the axis e_1 get their directions deflected to an essentially arbitrary direction (see figure 2). Therefore, in spite of the fact that the collisions

preserve the energy of the particles, the component w_2 of the particle velocities increases in a significant way for most of the collisions. As a consequence the increase of the velocities in the subsequent evolution by means of the shear term becomes much larger than before the collision.

We now introduce a simple model for the evolution of a particle system under the combined effect of shear and collisions containing some of the main properties of the evolution described above. The resulting model is simpler than the Boltzmann equation and it is possible to derive asymptotic formulae for the behaviour of its solutions.

We will assume that the particles of a system can be characterized by two real variables, namely $\zeta > 1$ and $\rho > 0$. We can think on ζ as the component $\frac{w_1}{|w|}$ of the velocity in the simple shear case and ρ as the absolute value of the velocity $|w|$. We assume that between collisions ζ increases at a constant rate. Notice that we can think also on ζ (more precisely $(\zeta - 1)$) as the time between collisions. On the other hand, we will assume that at the collision times the particle jumps to a new value of ρ, denoted as $\tilde{\rho}$ and given by $\tilde{\rho} = \rho\zeta$. The new value of ζ after the collision is reset to $\zeta = 1$. The collisions take place with the rate ε which typically will be assumed to be time dependent.

The particle distribution $f = f(t, \rho, \zeta)$ is then given by

$$\partial_t f + \partial_\zeta f = -\varepsilon(t)f \ , \ \ \zeta > 1, \ \rho > 0 \ , \ t > 0 \tag{3.40}$$

$$f(t, \rho, 1) = \varepsilon(t)\int_1^\infty f\left(t, \frac{\rho}{\zeta}, \zeta\right)\frac{\mathrm{d}\zeta}{\zeta}. \tag{3.41}$$

We will assume that the initial particle distribution is

$$f(0, \rho, \zeta) = f_0(\rho)\,\delta(\zeta - 1). \tag{3.42}$$

Notice that in this model we are implicitly assuming that the absolute value of the velocity for a particle characterized by the variables (ρ, ζ) is $\rho\zeta$. We will study the dynamics of the model (3.40)–(3.42), in general with a time dependent ε. However, we can also obtain a nonlinear version of (3.40)–(3.42) in order to mimic the property of the Boltzmann equation according to which for negative homogeneities of the kernel B the collision rate decreases for large particle velocities. In such nonlinear version of the model we consider

$$\partial_t f + \partial_\zeta f = -\varepsilon(t)f \ , \ \ \zeta > 1, \ \rho > 0 \ , \ t > 0 \tag{3.43}$$

$$f(t, \rho, 1) = \varepsilon(t)\int_1^\infty f\left(t, \frac{\rho}{\zeta}, \zeta\right)\frac{\mathrm{d}\zeta}{\zeta}. \tag{3.44}$$

with

$$\varepsilon(t) = \int_0^\infty \mathrm{d}\rho \int_1^\infty \mathrm{d}\zeta\, \frac{f(t, \rho, \zeta)}{\rho^a \zeta^a}, \quad a \in (0, 1). \tag{3.45}$$

The case $a \in (0, 1)$ plays a role analogous to the homogeneity of the kernel $\gamma \in (-1, 0)$ in the case of Simple Shear for the Boltzmann equation.

A difference between the models (3.40)–(3.42), (3.43)–(3.45) and the dynamics of the particles for homoenergetic solutions of Boltzmann equation in the case of simple shear is that the particles can move only in the direction of increasing ζ while in the Boltzmann case w_1 can be increasing or decreasing. Notice that the smallness of ε (and therefore the long free flights between collisions) makes reasonable to assume that the particles jump after each collision to $\zeta = 1$, because we assumed that the jump takes place within a radius of order $\tilde{\rho}$, since the length of the flight immediately later is typically much larger than $\tilde{\rho}$.

It is readily seen that the solutions of (3.40)–(3.42) (or (3.43)–(3.45)) satisfy

$$\partial_t \left(\int_0^\infty \mathrm{d}\rho \int_1^\infty \mathrm{d}\zeta \, f(t, \rho, \zeta) \right) = 0. \tag{3.46}$$

It is worth to notice that the Jacobian $\frac{\mathrm{d}\zeta}{\zeta}$ in (3.41) is due to the multiplicative structure of the jumps. This Jacobian plays a crucial role in the derivation of the mass conservation property (3.46).

The models (3.40)–(3.42) with $\varepsilon(t) \to 0$ as $t \to \infty$ or (3.43)–(3.45) have several analogies with the homoenergetic flows for the Boltzmann equation. The most relevant one is the existence of large particle flights which increase in a significant manner the energy of the particle, followed by rare collisions which transport the particle to a new state where the increase of energy due to long flights is much larger than before. We will describe some results concerning the asymptotics of the solutions of the models (3.40)–(3.42) and (3.43)–(3.45), which perhaps could shed some light about the type of behaviours arising in the homoenergetic flows of the Boltzmann equation in the cases in which the rate associated to the collision terms tends to zero but it is nonintegrable.

3.5.2. Reformulation of the model in an equivalent set of variables. We now reformulate the models (3.40)–(3.42) and (3.43)–(3.45) in an alternative form which will make simpler to study their long time asymptotics. We define $G(t, X, Z)$ by means of

$$f(t, \rho, \zeta) = \exp\left(-\int_0^t \varepsilon(\tau) \, \mathrm{d}\tau \right) G(t, X, Z) \ , \ \rho = \mathrm{e}^X \ , \ \zeta = \mathrm{e}^Z. \tag{3.47}$$

Then (3.40)–(3.42) become

$$\partial_t G + \mathrm{e}^{-Z} \partial_Z G = 0 \ , \ Z > 0 \, , \, X \in \mathbb{R} \tag{3.48}$$

$$G(t, X, 0) = \varepsilon(t) \int_0^\infty G(t, X - Z, Z) \, \mathrm{d}Z \tag{3.49}$$

$$G(0, X, Z) = G_0(X) \, \delta(Z). \tag{3.50}$$

We can reformulate (3.48)–(3.50) as an integral equation for the function $\Phi(t, X) = G(t, X, 0)$. Integrating by characteristics (3.48), (3.50) we obtain

$$G(t, X, Z) = \frac{G_0(X)}{1 + t} \delta(Z - \log(1 + t)) + G(t + 1 - \mathrm{e}^Z, X, 0)$$

$$= \frac{G_0(X)}{1 + t} \delta(Z - \log(1 + t)) + \Phi(t + 1 - \mathrm{e}^Z, X). \tag{3.51}$$

Using this formula in (3.49) we obtain

$$\Phi(t, X) = \frac{\varepsilon(t)}{1 + t} \int_0^\infty G_0(X - Z) \, \delta(Z - \log(1 + t)) \, \mathrm{d}Z$$

$$+ \varepsilon(t) \int_0^{\log(1+t)} \Phi(t + 1 - \mathrm{e}^Z, X - Z) \, \mathrm{d}Z$$

and using the change of variables $\mathrm{e}^Z - 1 = \xi$ we then obtain the integral equation

$$\Phi(t, X) = \frac{\varepsilon(t)}{1 + t} G_0(X - \log(1 + t)) + \varepsilon(t) \int_0^t \Phi(t - \xi, X - \log(1 + \xi)) \frac{\mathrm{d}\xi}{1 + \xi}. \tag{3.52}$$

In the case in which $\varepsilon(t)$ is given by (3.45) we obtain, using (3.47)

$$\varepsilon(t)\exp\left(\int_0^t \varepsilon(\tau)\,\mathrm{d}\tau\right) = \int_{-\infty}^{\infty} \mathrm{e}^{(1-a)X}\mathrm{d}X \int_0^{\infty} \mathrm{e}^{(1-a)Z}G(t,X,Z)\,\mathrm{d}Z$$

and using (3.51) we then obtain

$$\varepsilon(t)\exp\left(\int_0^t \varepsilon(\tau)\,\mathrm{d}\tau\right) = \frac{C_0}{(1+t)^a} + \int_{-\infty}^{\infty} \mathrm{e}^{(1-a)X}\mathrm{d}X \int_0^t \Phi(t-\xi,X)\,\frac{\mathrm{d}\xi}{(1+\xi)^a}$$

$$\tag{3.53}$$

where

$$C_0 = \int_{-\infty}^{\infty} G_0(X)\,\mathrm{e}^{(1-a)X}\mathrm{d}X. \tag{3.54}$$

We have then reduced the models (3.40)–(3.42) and (3.43)–(3.45) to the models (3.52) and (3.52)–(3.54) respectively. We now study the asymptotics of the solutions of these models. We begin studying (3.52) with constant ε.

3.5.3. The model (3.52) with constant ε.   The equation (3.52) can be explicitly solved using Fourier and Laplace transforms if $\varepsilon(t) = \varepsilon$ is a constant, i.e.

$$\Phi(t,X) = \frac{\varepsilon}{1+t}G_0(X - \log(1+t)) + \varepsilon\int_0^t \Phi(t-\xi,X - \log(1+\xi))\,\frac{\mathrm{d}\xi}{1+\xi}, \quad X \in \mathbb{R},\ t \geqslant 0.$$

$$\tag{3.55}$$

Actually we need to consider a more general class of problems. Given any $\beta \in \mathbb{R}$ we define functions

$$\Psi(t,X) = \Psi_\beta(t,X) = \Phi(t,X)\,\mathrm{e}^{\beta X}. \tag{3.56}$$

Then, formally, the functions Ψ solve the equations

$$\Psi(t,X) = \frac{\varepsilon}{(1+t)^{1-\beta}}H_0(X - \log(1+t)) + \varepsilon\int_0^t \Psi(t-\xi,X - \log(1+\xi))\,\frac{\mathrm{d}\xi}{(1+\xi)^{1-\beta}},$$

$$\tag{3.57}$$

for $X \in \mathbb{R}$ and $t \geqslant 0$. Here

$$H_0(X) = H_{0,\beta}(X) = G_0(X)\,\mathrm{e}^{\beta X}. \tag{3.58}$$

We will assume that G_0 decreases fast enough as $|X| \to \infty$ in order to guarantee the convergence of all the integrals appearing later. We use the following form of the Fourier transform in X

$$\psi(t,k) = \frac{1}{\sqrt{2\pi}}\int_{-\infty}^{\infty} \Psi(t,X)\,\mathrm{e}^{-ikX}\mathrm{d}X. \tag{3.59}$$

Notice that the Fourier transform $\psi(t,k)$ is defined if $\Psi(t,X)$ does not increase exponentially as $|X| \to \infty$. It is well known that the Fourier transform can be defined in the class of tempered

distributions. We will not make precise the spaces in which the functions Ψ are, but this could be made easily using the properties of Fourier and Laplace transforms in distribution spaces. (See for instance [12]).

Taking formally the Fourier transform in X of (3.57) we obtain

$$\psi(t,k) = \frac{\varepsilon}{(1+t)^{1-\beta+ik}} h_0(k) + \varepsilon \int_0^t \frac{\psi(t-\xi,k)\,d\xi}{(1+\xi)^{1-\beta+ik}} \tag{3.60}$$

where h_0 is the Fourier transform of H_0. In order to solve (3.60) we take the Laplace transform in time. We define the Laplace transform as

$$\tilde{\psi}(z,k) = \int_0^\infty \psi(t,k)\,e^{-zt}dt. \tag{3.61}$$

Then using (3.60) and the properties of the Laplace transform of a convolution we obtain

$$\tilde{\psi}(z,k)\left[1 - \varepsilon\Lambda(z,k)\right] = \varepsilon h_0(k)\Lambda(z,k)$$

where

$$\Lambda(z,k) = \Lambda_\beta(z,k) = \int_0^\infty \frac{e^{-zt}dt}{(1+t)^{1-\beta+ik}}. \tag{3.62}$$

Therefore, as long as $[1 - \varepsilon\Lambda(z,k)] \neq 0$ we obtain

$$\tilde{\psi}(z,k) = \frac{\varepsilon h_0(k)\Lambda(z,k)}{1 - \varepsilon\Lambda(z,k)}. \tag{3.63}$$

The Fourier modes with a given $k \in \mathbb{R}^3$ increase exponentially as $\exp(z_0(k;\varepsilon)t)$ where $z_0(k;\varepsilon)$ is the solution z of the equation

$$1 - \varepsilon\Lambda(z,k) = 0 \tag{3.64}$$

with the largest real part. We then need to understand the roots of the equation

$$\frac{1}{\varepsilon} = \int_0^\infty \frac{e^{-zt}dt}{(1+t)^{1-\beta+ik}}. \tag{3.65}$$

For any $\beta \geqslant 0$, there exists a unique root $z_0(0;\varepsilon) \in \mathbb{R}_+$ of (3.65) for $k = 0$. This follows from the fact that the function

$$z \to \Lambda(z,0) = \int_0^\infty \frac{e^{-zt}dt}{(1+t)^{1-\beta}}, \quad z \in \mathbb{R}_+ \tag{3.66}$$

is decreasing in z and it converges to infinity as $z \to 0^+$. Moreover, given any other root $z_0(k;\varepsilon)$ of (3.65) with $k \neq 0$ we have $\mathrm{Re}(z_0(k;\varepsilon)) < z_0(0;\varepsilon)$. Indeed, if $k \neq 0$ we can write

$$\int_0^\infty \frac{e^{-\mathrm{Re}(z_0(0;\varepsilon))t}dt}{(1+t)^{1-\beta}} = \frac{1}{\varepsilon} = \int_0^\infty \frac{e^{-zt}dt}{(1+t)^{1-\beta+ik}} < \int_0^\infty \frac{e^{-\mathrm{Re}(z_0(k;\varepsilon))t}dt}{(1+t)^{1-\beta}}$$

and using the fact that the function defined in (3.66) is decreasing we obtain $\mathrm{Re}(z_0(0;\varepsilon)) > \mathrm{Re}(z_0(k;\varepsilon))$.

Moreover, we can compute the asymptotics of $z_0(0;\varepsilon)$ using the asymptotics

$$\int_0^\infty \frac{e^{-zt}dt}{(1+t)^{1-\beta}} = \frac{1}{z^\beta}\int_0^\infty \frac{e^{-\zeta}d\zeta}{(z+\zeta)^{1-\beta}} \sim \frac{\Gamma(\beta)}{z^\beta} \text{ as } z \to 0^+$$

whence

$$z_0\left(0;\varepsilon\right) \sim \left(\Gamma\left(\beta\right)\varepsilon\right)^{\frac{1}{\beta}} \quad \text{as } \varepsilon \to 0 \text{ if } \beta > 0. \tag{3.67}$$

If $\beta = 0$, we obtain that $z_0\left(0;\varepsilon\right)$ is exponentially small, due to the logarithmic divergence of the integral in (3.66) as $z \to 0^+$, but we will not need the detailed analysis of β in such a case.

Notice that using (3.63) and (3.67) as well as the inversion formula for the Laplace transform we obtain, for $k = 0$, the following approximation for small ε

$$\psi\left(t,0\right) \sim \frac{h_0\left(0\right)}{B\varepsilon} \exp\left(\left(\Gamma\left(\beta\right)\varepsilon\right)^{\frac{1}{\beta}}t\right) \quad \text{as } t \to \infty$$

where

$$B = -\frac{\partial\Lambda\left(z_0\left(0;\varepsilon\right),0\right)}{\partial z} = \int_0^\infty \frac{\mathrm{e}^{-z_0(0;\varepsilon)t}t}{\left(1+t\right)^{1-\beta}}\mathrm{d}t \sim \frac{\Gamma\left(\beta+1\right)}{\left(z_0\left(0;\varepsilon\right)\right)^{1+\beta}} = \frac{\beta}{\left(\Gamma\left(\beta\right)\right)^{\frac{1}{\beta}}}\frac{1}{\varepsilon^{1+\frac{1}{\beta}}} \quad \text{as } \varepsilon \to 0. \tag{3.68}$$

Then

$$\psi\left(t,0\right) \sim \frac{\left(\Gamma\left(\beta\right)\varepsilon\right)^{\frac{1}{\beta}}}{\beta}h_0\left(0\right)\exp\left(\left(\Gamma\left(\beta\right)\varepsilon\right)^{\frac{1}{\beta}}t\right) \quad \text{as } t \to \infty.$$

Using the definitions of the Fourier transform (cf (3.59)) and of the functions H_0, Ψ (cf (3.56), (3.58)) we obtain

$$\int_{-\infty}^\infty \Phi\left(t,X\right)\mathrm{e}^{\beta X}\mathrm{d}X \sim \frac{\left(\Gamma\left(\beta\right)\varepsilon\right)^{\frac{1}{\beta}}}{\beta}\exp\left(\left(\Gamma\left(\beta\right)\varepsilon\right)^{\frac{1}{\beta}}t\right)\int_{-\infty}^\infty G_0\left(X\right)\mathrm{e}^{\beta X}\mathrm{d}X \quad \text{as } t \to \infty. \tag{3.69}$$

The formula (3.69) provides a large amount of information about the distribution of mass of the function $\Phi\left(t,X\right)$ as $t \to \infty$. It is interesting to remark that the integrals $\int_{-\infty}^\infty \Phi\mathrm{e}^{\beta X}\mathrm{d}X$ increase at a different rate for different values of β. Due to the changes of variables in (3.47) this would imply that different moments of f increase at a different rate. As indicated in previous subsections this is incompatible with a self-similar behaviour for f.

Actually, it is possible to obtain some additional information about the transport of mass towards $X \to \infty$ for the solutions of (3.57) deriving the asymptotics of $z_0\left(k;\varepsilon\right)$ as $k \to 0$ ssby means of (3.65). This yields

$$z_0\left(k;\varepsilon\right) \sim z_0\left(0;\varepsilon\right) + A_1^\varepsilon \mathrm{i}k - A_2^\varepsilon k^2 \quad \text{as } k \to 0 \tag{3.70}$$

for suitable real functions A_1^ε, $A_2^\varepsilon > 0$ depending on ε and β. Using the formula for the inversion of Fourier as well as (3.70) it is possible to obtain an expansion for $\Phi\left(X,t\right)$ with the form

$$\Phi\left(t,X\right) \sim \frac{\varepsilon h_0\left(0\right)\Lambda\left(z_0\left(0;\varepsilon\right),0\right)}{B_\varepsilon\left(0\right)}\frac{\exp\left(z_0\left(0;\varepsilon\right)t\right)}{\sqrt{A_2^\varepsilon t\mathrm{e}^{\beta X}}}Q_\varepsilon\left(\frac{X + A_1^\varepsilon t}{\sqrt{A_2^\varepsilon t}}\right) \quad \text{as } t \to \infty, \tag{3.71}$$

where

$$Q_\varepsilon(\xi) = \frac{1}{\sqrt{2}} \exp\left(-\frac{\xi^2}{4}\right).$$

We want to give a more detailed expression of the formula (3.71).

We will derive the asymptotics for $\Phi(t, X)$ using (3.56), namely $\Psi(t, X) = \Phi(t, X) e^{\beta X}$. We need to compute the asymptotics for $\Psi(t, X)$. To this end we invert the Laplace transform $\tilde{\psi}(z, k)$ in (3.63), i.e. we compute

$$\psi(t, k) = \frac{1}{2\pi i} \int_C \frac{\varepsilon h_0(k) \Lambda(z, k)}{1 - \varepsilon \Lambda(z, k)} e^{zt} dz. \tag{3.72}$$

There is a zero of $(1 - \varepsilon \Lambda(z, k))$ at $z = z_0(k; \varepsilon)$. We assume that:

$$1 - \varepsilon \Lambda(z, k) = B_\varepsilon(k)(z - z_0(k; \varepsilon))[1 + o(1)] \quad \text{as } z \to z_0(k; \varepsilon).$$

Thus, we can compute the integral in (3.72) using residues. We observe that there would be additional contributions to the integral, but they are smaller as $t \to \infty$. We then obtain the asymptotics:

$$\psi(t, k) \sim \frac{\varepsilon h_0(k) \Lambda(z_0(k; \varepsilon), k)}{B_\varepsilon(k)} \exp(z_0(k; \varepsilon) t) \quad \text{as } t \to \infty. \tag{3.73}$$

The function $B(k)$ is obtained by means of the derivative of $\Lambda(z, k)$ (cf (3.68)) in the case $k = 0$. The formula of $B(k)$ is:

$$B_\varepsilon(k) = \int_0^\infty \frac{e^{-z_0(k; \varepsilon) t}}{(1 + t)^{1 - \beta + ik}} dt.$$

We are computing the asymptotics of the solutions as $k \to 0$. We use the asymptotic formula (3.70). If we fix ε and we take $k \to 0$ we obtain that the function $B_\varepsilon(k)$ is continuous in k (for each $\varepsilon > 0$ fixed) and we have $\lim_{k \to 0} B_\varepsilon(k) = B_\varepsilon(0)$.

Therefore, taking the asymptotics $k \to 0$, we obtain the following approximation for (3.73):

$$\psi(t, k) \sim \frac{\varepsilon h_0(0) \Lambda(z_0(0; \varepsilon), 0)}{B_\varepsilon(0)} \exp\left(\left[z_0(0; \varepsilon) + A_1^\varepsilon ik - A_2^\varepsilon k^2\right] t\right) \tag{3.74}$$

where we use (3.70) in the approximation of the exponent. We assume also that h_0 is smooth and $h_0(0) > 0$.

We can obtain now the inverse of the Fourier transform to derive the asymptotics of $\Psi(t, X)$ and then $\Phi(t, X)$ using (3.56). We have:

$$\Psi(t, X) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^\infty \psi(t, k) e^{ikX} dk.$$

We then obtain, using (3.74), the asymptotics:

$$\Psi(t, X) \sim \frac{1}{\sqrt{2\pi}} \frac{\varepsilon h_0(0) \Lambda(z_0(0; \varepsilon), 0)}{B_\varepsilon(0)} \int_{-\infty}^\infty \exp\left(\left[z_0(0; \varepsilon) + A_1^\varepsilon ik - A_2^\varepsilon k^2\right] t\right) e^{ikX} dk$$

$$= \frac{1}{\sqrt{2\pi}} \frac{\varepsilon h_0(0) \Lambda(z_0(0; \varepsilon), 0)}{B_\varepsilon(0)} \exp(z_0(0; \varepsilon) t) \int_{-\infty}^\infty \exp\left(-A_2^\varepsilon k^2 t\right) e^{ik\left(X + A_1^\varepsilon t\right)} dk$$

and inverting the Fourier transform we get (3.71). Using this formula and (3.56) we obtain (3.69).

Using these expansions for arbitrary values of β it is possible to derive a large amount of information about the asymptotics of $\Phi(t, X)$ in different regions of the plane (X, t) as $t \to \infty$. However, we will not use this type of detailed asymptotic formulae in this paper.

3.5.4. The model (3.52) with slowly changing ε. We now examine the equation (3.52) assuming that the function $\varepsilon(t)$ changes slowly. By this we mean that $|\partial_t \varepsilon(t)| \ll \varepsilon(t)$. A typical behaviour for $\varepsilon(t)$ would be $\varepsilon(t) \sim \frac{A}{t}$ as $t \to \infty$ for some constant $A > 0$. Suppose that for any $\beta \geqslant 0$ we define Ψ is as in (3.56). Actually, we are interested in the asymptotics of $\int_{-\infty}^{\infty} \Psi(t, X) \, dX = \lambda(t) = \lambda_\beta(t)$. Then, using (3.57) we obtain

$$\lambda(t) = \frac{C_\beta \varepsilon(t)}{(1+t)^{1-\beta}} + \varepsilon(t) \int_0^t \frac{\lambda(t-\xi) \, d\xi}{(1+\xi)^{1-\beta}} \qquad (3.75)$$

where

$$C_\beta = \int_{-\infty}^{\infty} H_0(X) \, dX.$$

We look for solutions of (3.75) with the form

$$\lambda(t) = \exp\left(\int_0^t z(\tau) \, d\tau\right)$$

for some suitable function $z(\tau)$ to be determined. Then

$$1 = \frac{C_\beta \varepsilon(t) \exp\left(-\int_0^t z(\tau) \, d\tau\right)}{(1+t)^{1-\beta}} + \varepsilon(t) \int_0^t \frac{\exp\left(-\int_{t-\xi}^t z(\tau) \, d\tau\right) d\xi}{(1+\xi)^{1-\beta}}. \qquad (3.76)$$

The first term on the right can be expected to be exponentially small compared with the second. On the other hand if $\varepsilon(t)$ changes slowly in the form indicated above we expect $z(\tau)$ to be approximately given by $z_0(0; \varepsilon(t))$. Indeed, if we assume that $z(\tau)$ changes slowly in τ and we neglect the first term on the right-hand side of (3.76) we obtain the approximation

$$\frac{1}{\varepsilon(t)} = \int_0^t \frac{\exp(-z(t)\xi)}{(1+\xi)^{1-\beta}} d\xi. \qquad (3.77)$$

Suppose that $z(t) \to 0$ as $t \to \infty$. We can then approximate the integral on the right-hand side of (3.77) in the same manner as (3.65), i.e. we write

$$\int_0^t \frac{\exp(-z(t)\xi)}{(1+\xi)^{1-\beta}} d\xi = \frac{1}{z(t)} \int_0^{\frac{t}{z(t)}} \frac{\exp(-y)}{\left(1+\frac{y}{z(t)}\right)^{1-\beta}} dy \sim \frac{1}{(z(t))^\beta} \int_0^\infty \frac{\exp(-y)}{y^{1-\beta}} dy = \frac{\Gamma(\beta)}{(z(t))^\beta}$$

whence, arguing as in the derivation of (3.67),

$$z(t) \sim z_0(0; \varepsilon(t)) \sim (\Gamma(\beta)\varepsilon(t))^{\frac{1}{\beta}} \quad \text{as } \varepsilon \to 0 \text{ if } \beta > 0. \qquad (3.78)$$

In order to check the validity of the approximation we just need to check the assumptions made in its derivation. The two assumptions made in the derivation of (3.78) are the following ones:

$$\frac{C_\beta \varepsilon(t)}{(1+t)^{1-\beta}} \ll \lambda(t) \quad \text{as } t \to \infty \qquad (3.79)$$

and

$$\int_0^t \frac{\exp\left(-\int_{t-\xi}^t z(\tau)\,\mathrm{d}\tau\right)\mathrm{d}\xi}{(1+\xi)^{1-\beta}} \sim \int_0^t \frac{\exp\left(-z(t)\,\xi\right)}{(1+\xi)^{1-\beta}}\mathrm{d}\xi \quad \text{as } t \to \infty. \qquad (3.80)$$

The approximation (3.80) holds, assuming that $z(t)$ behaves like (3.78) if $\varepsilon(t) \sim \frac{A}{t}$ as $t \to \infty$ and $\beta > 1$. Indeed, in that case we have

$$\int_0^t \frac{\exp\left(-\int_{t-\xi}^t z(\tau)\,\mathrm{d}\tau\right)}{(1+\xi)^{1-\beta}}\mathrm{d}\xi \sim \int_0^t \frac{\exp\left(-(\Gamma(\beta)A)^{\frac{1}{\beta}}\int_{t-\xi}^t \tau^{-\frac{1}{\beta}}\,\mathrm{d}\tau\right)}{(1+\xi)^{1-\beta}}\mathrm{d}\xi$$

$$= \int_0^t \frac{\exp\left(-\frac{(\Gamma(\beta)A)^{\frac{1}{\beta}}\beta}{\beta-1}\left[(t)^{-\frac{1}{\beta}+1} - (t-\xi)^{-\frac{1}{\beta}+1}\right]\right)}{(1+\xi)^{1-\beta}}\mathrm{d}\xi$$

$$= t\int_0^1 \frac{\exp\left(-\frac{(\Gamma(\beta)A)^{\frac{1}{\beta}}\beta}{\beta-1}(t)^{-\frac{1}{\beta}+1}\left[1 - (1-\eta)^{-\frac{1}{\beta}+1}\right]\right)}{(1+t\eta)^{1-\beta}}\mathrm{d}\eta$$

and this integral can be approximated if $t \to \infty$, using the Laplace method (see [4]), by means of the right-hand side of (3.80). On the other hand (3.79) holds in this case, since $\lambda(t)$ tends exponentially to infinity.

Nevertheless, if $\beta < 1$ and $\varepsilon(t) \sim \frac{A}{t}$ as $t \to \infty$ the solution (3.78) would not describe the asymptotics of $\lambda(t)$ because the approximation (3.79) would fail. In this case we will try a solution of (3.76) with the form

$$\lambda(t) = \mathrm{e}^{J(t)}. \qquad (3.81)$$

We consider the case with $\varepsilon(t) \sim \frac{A}{t}$. It will turn out that in this case we will not be able to assume that $\frac{C_\beta \varepsilon(t)}{(1+t)^{1-\beta}} \ll \lambda(t)$ as $t \to \infty$ (see (3.79)). We have and we would have the approximated problem

$$1 = \frac{C_\beta \varepsilon(t)}{(1+t)^{1-\beta}\lambda(t)} + \frac{A}{t}\int_0^t \frac{\exp\left(J(t-\xi) - J(t)\right)}{\xi^{1-\beta}}\mathrm{d}\xi. \qquad (3.82)$$

We can obtain an approximate solution of (3.82) in the form

$$J(t) = -B\left[\log(t+1)\right] \qquad (3.83)$$

for some suitable $B > 0$. Then (3.82) becomes for large t

$$1 = \frac{C_\beta \varepsilon(t)(t+1)^B}{(1+t)^{1-\beta}} + \frac{A(t+1)^B}{t}\int_0^t \frac{1}{\xi^{1-\beta}}\frac{1}{(t-\xi+1)^B}\mathrm{d}\xi.$$

If $B > 1$ we can approximate the right-hand side of this equation as

$$\frac{C_\beta A(t+1)^B}{(1+t)^{1-\beta}t} + \frac{A(t+1)^B}{t}\frac{1}{t^{1-\beta}}\int_0^t \frac{1}{(t-\xi+1)^B}\mathrm{d}\xi = \frac{AC_0(t+1)^B}{t^{2-\beta}}$$

and then we obtain a possible solution of (3.82) if $B = 2 - \beta$ which is larger than one, and therefore gives a consistent asymptotics. Notice, however, that the determination of the multiplicative constants, in particular C_0 requires a more careful analysis, because this quantity is

really determined by the values of $\lambda(t)$ with t of order one. A more careful examination of the argument shows that

$$C_0 \simeq C_\beta A + \int_0^\infty \lambda(t) \, \mathrm{d}t.$$

In any case, we just indicate at this point that the assumptions (3.79), (3.80) which are at the basis of the approximation of the solution $\lambda(t)$ by means of an adiabatic change of the eigenvalue $z(t)$ cannot be given by granted for arbitrary values of β and $\varepsilon(t)$. In particular, a careful analysis of the conditions (3.79), (3.80) is needed in each particular case.

3.5.5. The model (3.52)–(3.54). Finally we derive asymptotic formulae for the solutions $\varepsilon(t)$ of the problem (3.52)–(3.54). To this end we multiply (3.52) by $\mathrm{e}^{(1-a)X}$ and integrating in X we obtain the following equation for $\lambda(t) = \int_{-\infty}^\infty \mathrm{e}^{(1-a)X} \Phi(t, X) \, \mathrm{d}X$ (cf also (3.75))

$$\lambda(t) = \frac{C_a \varepsilon(t)}{(1+t)^a} + \varepsilon(t) \int_0^t \frac{\lambda(t-\xi) \, \mathrm{d}\xi}{(1+\xi)^a} \tag{3.84}$$

with

$$C_a = \int_{-\infty}^\infty G_0(X) \, \mathrm{e}^{(1-a)X} \mathrm{d}X \text{ and } 0 < a < 1.$$

On the other hand (3.53) becomes

$$\varepsilon(t) \exp\left(\int_0^t \varepsilon(\tau) \, \mathrm{d}\tau\right) = \frac{C_0}{(1+t)^a} + \int_0^t \frac{\lambda(t-\xi) \, \mathrm{d}\xi}{(1+\xi)^a}. \tag{3.85}$$

We now use the methods in section 3.5.4 to approximate $\lambda(t)$. We will obtain an asymptotics with the form $\varepsilon(t) \sim \frac{A}{t}$, something that is not surprising, because the form of (3.85) suggests the behaviour $\int_0^t \varepsilon(\tau) \, \mathrm{d}\tau \sim K \log(t)$. Since $a \in (0, 1)$ we cannot use the method yielding (3.78) but instead the method yielding (3.81) and (3.83). Suppose that $\varepsilon(t) \sim \frac{A}{t}$ (something that we will check '*a posteriori*'). Then, using (3.81) and (3.83) we obtain

$$\lambda(t) \sim \frac{C}{t^{1+a}} \text{ as } t \to \infty. \tag{3.86}$$

On the other hand, we can rewrite (3.85) as

$$\frac{\mathrm{d}}{\mathrm{d}t}\left(\exp\left(\int_0^t \varepsilon(\tau) \, \mathrm{d}\tau\right)\right) = \frac{C_0}{(1+t)^a} + \int_0^t \frac{\lambda(t-\xi) \, \mathrm{d}\xi}{(1+\xi)^a}. \tag{3.87}$$

Combining (3.86) and (3.87) we obtain the approximation

$$\frac{\mathrm{d}}{\mathrm{d}t}\left(\exp\left(\int_0^t \varepsilon(\tau) \, \mathrm{d}\tau\right)\right) \sim \frac{K}{t^a} \text{ as } t \to \infty$$

whence $\int_0^t \varepsilon(\tau) \, \mathrm{d}\tau \sim \log\left(t^{1-a}\right)$ as $t \to \infty$. Then $\varepsilon(t) \sim \frac{(1-a)}{t}$ as $t \to \infty$. We then recover the ansatz made for $\varepsilon(t)$ with $A = (1 - a)$.

3.5.6. Conclusions on the toy model. The model (3.40)–(3.42) either with ε constant or given by (3.45) gives some information about the particle distribution which evolves according to the combined effect of particle transport and rare collisions. It is interesting to remark that even in the case of constant collision rate ε, different moments of the function f are asymptotically given by different functions in a way that is not compatible with a self- similar behaviour for the distribution f. In the case of the model (3.40)–(3.42) with ε given by (3.45) we formally obtained an asymptotic formula for the long time behaviour of the function $\varepsilon(t)$. More precisely, we show that $\varepsilon(t) \sim \frac{(1-a)}{t}$ as $t \to \infty$. Notice that the lack of integrability of this rate as $t \to \infty$ implies that a given particle experiences infinitely many collisions as $t \to \infty$. It would be relevant to prove rigorously this asymptotic behaviour and to extend these results to the full nonlinear Boltzmann equation.

3.6. A remark on the homoenergetic solutions for the Fokker–Planck operator

The problem of some particular homoenergetic solutions for a different kinetic equation, namely the Fokker–Planck equation has been considered in [20]. More precisely, instead of considering the Boltzmann equation (1.3) they consider

$$\partial_t f + v \partial_x f = \Delta_v f + \frac{1}{\varepsilon(x)} \partial_v \left(f(v - V(x)) \right), \tag{3.88}$$

with $V(x)$ and $\varepsilon(x)$ as in (2.15) and (2.16) respectively. In [20] the case of simple shear and higher dimensional generalizations of it are considered. Notice that this case, from a dimensional analysis point of view, corresponds to the hyperbolic-dominated case considered in this paper. The following solution of (3.88) is obtained and its stability properties are described.

$$f(t, x, v) = (\det \eta(t)) G(p) \tag{3.89}$$

with

$$p = \eta(t) \left(v + Kx_2(1, 0)^T \right),$$

$$\eta(t) = \frac{1}{Kt^{\frac{3}{2}}} \begin{pmatrix} \sqrt{3} & 3 \\ 3 & 2Kt \end{pmatrix} \tag{3.90}$$

and

$$G(p) = (4\pi)^{-\frac{1}{2}} \exp\left(-\frac{1}{4}|p|^2 \right).$$

It is interesting to remark that the solution (3.89) is a stretched Maxwellian. This is very different from the type of behaviour that we obtained for the simplified model introduced in section 3.5. Note also that the models (1.3) and (3.88) are very different from the physical point of view in the hyperbolic-dominated regime. Indeed, in the Boltzmann case the mean free flight time is much larger than the characteristic time in which important shear takes place. On the contrary, the Fokker–Planck dynamics implicitly assumes that the mean free flight time is very small.

4. Entropy formulae

Homoenergetic solutions are characterized by constant values in space of the particle density $\rho = \rho(t)$ and internal energy $\varepsilon = \varepsilon(t)$. We are now interested in the form of another relevant

thermodynamic magnitude, namely the entropy that, for the Boltzmann equation, we identify with minus the $H-$function.

Let be $f = f(t,x,v)$ the velocity distribution. We obtain the following entropy density for particle at a given point x

$$\frac{s(t,x)}{\rho(t)} = -\frac{1}{\rho(t)}\int f(t,x,v)\log(f(t,x,v))\,\mathrm{d}^3v.$$

Using (2.1) it follows that the entropy density for particle is independent of x and it is given by

$$\frac{s(t)}{\rho(t)} = -\frac{1}{\rho(t)}\int_{\mathbb{R}^3} g(t,w)\log(g(t,w))\,\mathrm{d}^3w. \tag{4.1}$$

In a previous paper (see [18], section 7) we showed that in the case of self-similar solutions the formulae for entropy for particle have some analogies with the corresponding formulae for equilibrium distributions, in spite of the fact that the distributions obtained there deal with nonequilibrium situations. This was due to the fact that to a large extent the entropy formulae depend on the scaling properties of the distributions.

Moreover, there is a case in which the analogy between the entropy formulae for the equilibrium case and the considered solutions is the largest which corresponds, nonsurprisingly, to the case in which the particle distribution is given by Hilbert expansions (see [19]). Indeed, we notice that both in the cases of solutions given by time-dependent Maxwellian distributions or self-similar solutions we can approximate $g(t,w)$ as

$$g(t,w) \sim \frac{1}{a(t)}G\left(\frac{w}{\lambda(t)}\right) \quad \text{as } t \to \infty \tag{4.2}$$

for suitable functions $a(t)$, $\lambda(t)$ which are related to the particle density and the average energy of the particles.

In the case of solutions given by Hilbert expansions the distribution G is a Maxwellian, which can be assumed to be normalized to have density one and temperature one. Moreover, we will assume also that the mass of the particles is normalized to $m = 2$ in order to get simpler formulae. This implies that the Maxwellian distribution takes the form $G_M(\xi) = \frac{\mathrm{e}^{-|\xi|^2}}{\pi^{\frac{3}{2}}}$.

We recall that in [18] it has been obtained that

$$\frac{s}{\rho} = \log\left(\frac{\mathrm{e}^{\frac{3}{2}}}{\rho}\right) + C_G \tag{4.3}$$

where C_G is

$$C_G = -\frac{\int G\log(G)\,\mathrm{d}\xi}{\int G(\xi)\,\mathrm{d}\xi} - \log\left[\frac{\left(\int |\xi|^2 G\mathrm{d}\xi\right)^{\frac{3}{2}}}{\left(\int G(\xi)\,\mathrm{d}\xi\right)^{\frac{5}{2}}}\right], \tag{4.4}$$

and $\frac{s}{\rho} \to \infty$ as $t \to \infty$. The formula (4.3) has the same form as the usual formula of the entropy for ideal gases, except for the value of the constant C_G. In the case of solutions given by Hilbert expansions the value of C_G is the same as the one in the formula of the entropy for ideal gases. Therefore, in the case of the solutions obtained in [19] which can be approximated by Hilbert expansions, the asymptotic formula for the entropy by particle is the same as the one for ideal gases.

In the case of solutions corresponding to a hyperbolic-dominated behaviour the formula of the entropy does not necessarily resemble the formula of the entropy for ideal gases, because in general the scaling properties of the particle distributions are very different from the ones taking place in the case of gases described by Maxwellian distributions.

For instance, if the homoenergetic flow is a homogeneous dilatation (cf section 3.1) the formula (4.3) holds with a constant C_G which depends on the initial particle distribution G_0. However, in this case, $\frac{s}{\rho}$ converges to a finite limit as $t \to \infty$ and therefore the contribution of the constant C_G in (4.3) is of the same order of magnitude as each of the other two terms.

In the case of simple shear with $\gamma < -1$ (cf section 3.3) we obtain the following formulae for large t (cf (3.11)–(3.13))

$$\rho = \int G_0 \left(\eta_1, w_2, w_3\right) d\eta_1 dw_2 dw_3$$

$$\varepsilon \sim K^2 t^2 \int G_0 \left(\eta_1, w_2, w_3\right) \left(w_2\right)^2 d\eta_1 dw_2 dw_3$$

$$s = -\int_{\mathbb{R}^3} G_0 \left(\eta_1, w_2, w_3\right) \log \left(G_0 \left(\eta_1, w_2, w_3\right)\right) d\eta_1 dw_2 dw_3. \tag{4.5}$$

Notice that (4.5) implies that the entropy of the distribution does not increase as $t \to \infty$, something that it is not surprising given that the role of the collisions is negligible. The average energy of the molecules increases due to the shear, but the entropy does not increase. Therefore, (4.3) holds with a constant C_G depending on the solution itself but, since the three terms in the equation are of the same order of magnitude as in the case of homogeneous dilatation, the formula does not give much information.

In the case of cylindrical dilatation the asymptotic behaviour of G is described by (3.6), i.e.

$$G \left(\tau, w\right) = e^{2\tau} G_\infty \left(e^\tau w_1, e^\tau w_2, w_3\right).$$

Then s is given by

$$s = -\int_{\mathbb{R}^3} e^{2\tau} G_\infty \left(e^\tau w_1, e^\tau w_2, w_3\right) \log G_\infty \left(e^\tau w_1, e^\tau w_2, w_3\right) dw$$

$$= -\int_{\mathbb{R}^3} G_\infty \left(\eta_1, \eta_2, w_3\right) \log G_\infty \left(\eta_1, \eta_2, w_3\right) d\eta_1 d\eta_2 dw_3.$$

We then obtain the same situation as in the case of planar shear (with $K = 0$), i.e. the entropy does not increase much for large values of t and its limit value is much dependent on the initial particle distribution.

In the case of combined orthogonal shears (cf section 3.4) we do not have much information about the distribution of particles, but we have argued that this distribution cannot be expected to be self-similar, and very likely the particle distributions and energy distributions are concentrated in different scales of $|w|$. Therefore, it is unlikely that formulae like (4.3) could be satisfied in such cases.

5. Concluding remarks

We have described in [18, 19] and in this paper several examples of long time asymptotics for homoenergetic solutions of the Boltzmann equation. This particular class of solutions exhibits a rich variety of possible asymptotic behaviours.

As discussed in [19] the key feature which distinguishes the different asymptotic behaviours is the relative size of the collision term and the hyperbolic term in the equation satisfied by the homoenergetic flows (cf (1.9)). The situation in which the collision terms are the dominant ones for large times has been studied in [19]. The case in which there is a balance between hyperbolic and collision terms has been rigorously analysed in [18]. In this paper we considered the case in which the hyperbolic terms are the dominant ones as $t \to \infty$.

When the hyperbolic terms are much larger than the collision terms the resulting solutions yield much more complex behaviours than the ones that we have obtained in the previous cases. One of the reasons for this is that in some cases the description of the asymptotic behaviour of the solutions is a singular perturbation problem, in which the collision term is very small but plays a crucial role determining the behaviour of the solutions for large times, because the collisions, in spite of their smallness, yield huge modifications of the geometry of the velocity distributions. In other cases we have found that the collisions are so small that their effect becomes irrelevant as $t \to \infty$. These are situations in which the collision rate becomes so small that the expected number of collisions for a given particle is bounded as $t \to \infty$. In these cases we say that we have 'frozen collisions'.

As it might be seen in this paper, in the hyperbolic-dominated case, the detailed understanding of the particle distributions for long times is largely open and challenging. The analysis of these flows suggest many new interesting mathematical questions which deserve further investigation.

Acknowledgments

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